MAT 267: Ordinary Differential Equations Final Assessment Topics, 2021

• **Basic concepts:** Solution of an ODE; the general solution. Initial-value problems. Existence and uniqueness. How to write a higher-order equation as a first-order system

• Scalar first-order equations

Slope field, solution curves

Separation of variables. Exact equations

Autonomous equations: Equilibria and stability. Phase portraits

Consequences of existence and uniqueness. Examples of non-uniqueness, non-existence, and finite-time blow-up

• Linear systems

General theory: The superposition principle and its consequences. The solution space of a homogeneous equation. The general solution of an inhomogeneous equation

Eigenvalues and eigenvectors: How they give rise to particular solutions $e^{t\lambda}v$. Eigenvalues determine the dynamics (Re λ describes growth or decay, Im λ describes frequency of oscillation), while eigenvectors determine the geometry (including stable and unstable directions). Multiplicity

Planar systems x' = Ax: Classification by type (saddle, node, center, spiral) and stability. Sources and sinks. Phase portraits (using eigenvalues and eigenvectors)

Higher-dimensional systems x' = Ax: Diagonalization and Jordan canonical form. The general solution. How to obtain real solutions from complex ones; Matrix exponentials e^{tA}

Duhamel's formula for solving x' = Ax + f(t)

Higher order equations (constant-coefficent and Euler-Cauchy type). Mass-spring systems

• Existence, uniqueness, and continuous dependence

Picard iteration. Local vs. global existence; maximal time of existence

Consequences of existence and uniqueness

The dynamical system $(\Phi_t)_{t\in\mathbb{R}}$ generated by a system x' = f(x). The semigroup property. Vector fields and diffeomorphims

• Linearization and stability

Equilibria: Nonlinear sources, sinks, and saddles; hyperbolicity. Topological conjugacy

• Global nonlinear techniques

Nullclines

Definition of *stable*, *unstable*, *asymptotically stable*

Lyapunov functions. Gradient flows and Hamiltonian systems

Positive and negative invariance, α - and ω -limit sets