

# MAT 1060: Partial Differential Equations I

## Assignment 3, October 6 2009

Read Chapter 2 to the end.

Please hand in to Ehsan in on Wednesday, October 21:

- Chapter 2 (p. 85): Problems 15, 16, 17, 18;

and the additional problems:

- *Lorentz invariance of the wave equation in  $\mathbb{R}^3$ .*

For  $z = (x, t) \in \mathbb{R}^n \times \mathbb{R}$ , consider the quadratic form  $m(z) = |x|^2 - t^2$ . A **Lorentz transformation** is an invertible linear transformation  $L : \mathbb{R}^{n+1} \rightarrow \mathbb{R}^{n+1}$  that satisfies

$$m(L(z)) = m(z), \quad (z \in \mathbb{R}^4).$$

Lorentz transformations form a group, i.e., the product and the inverse of Lorentz transformations is again a Lorentz transformation. (Why?)

(a) Let  $\Gamma$  be the diagonal  $(n+1) \times (n+1)$ -matrix with  $\Gamma_{ii} = 1$  for  $i \leq n$  and  $\Gamma_{n+1, n+1} = -1$ . Show that  $L$  is a Lorentz transformation, if and only if its matrix satisfies  $L^t \Gamma L = \Gamma$ . What can you say about the determinant of  $L$ ?

(b) If  $L$  is a Lorentz transformation, and  $v(z) = u(L(z))$ , show that

$$u_{tt} - \Delta u = v_{tt} - \Delta v.$$

*Hint:* Let  $\phi$  be a smooth function with compact support on  $\mathbb{R}^n$ , and consider the integral

$$I(u) = \int \int (u_{tt} - \Delta u) \phi(x, t) \, dx dt.$$

Integrate by parts and change variables.

*Remarks:* (i) The quadratic form  $m$  is called the **Minkowski metric** on  $\mathbb{R}^4$ . It is used to define the geometry of space-time in the Theory of Special Relativity. A vector  $z$  is called **timelike** if  $m(z) < 0$ , **spacelike** if  $m(z) > 0$ , and **Null** (or **characteristic**) if  $m(v) = 0$ .

(ii) The Lorentz transformations are the fundamental symmetries of Minkowski space, analogous to the orthogonal transformations on Euclidean space. An important difference is that the Lorentz group is non-compact, while the orthogonal group is compact. Can you see, why?

- *(Alternate proof of the maximum principle).*

Let  $u$  be a smooth real-valued function on  $\mathbb{R}^n$ . Suppose that

$$-\Delta u + b(x) \cdot Du \leq 0, \quad x \in U,$$

where  $U$  is a bounded set, and  $b$  is a bounded vector-valued function on  $U$ . Prove that  $u$  satisfies the weak maximum principle, i.e., it assumes its maximum on the boundary.

*Hint:* Consider the function

$$v(x) = u(x) + \varepsilon e^{\lambda x_1},$$

and choose  $\lambda > 0$  so that  $-\Delta v(x) + b(x) \cdot Dv(x) < 0$ .

*Remarks:* (i) A careful analysis shows that  $u$  satisfies the *strict* maximum principle, see Chapter 6.4.2. The proof remains valid, if the Laplacian is replaced by a differential operator of the form

$$Lu = \sum_{i,j=1}^n a_{ij}(x) D_i D_j u,$$

where the functions  $a_{ij}$  are smooth and bounded, the matrix  $A(x) = (a_{ij}(x))_{i,j=1}^n$  is symmetric, and its eigenvalues lie in some interval  $[c, C]$ , where  $c$  and  $C$  are positive constants.

(ii) Maximum principles are particularly useful in nonlinear problems, where exact solutions are usually not available, but they are largely limited to elliptic and parabolic second-order equations for a single real-valued function.

(iii) References: The strong maximum principle is due to Hopf (1927). Good modern sources are “Maximum Principles in Differential Equations”, by Protter and Weinberger (book; Springer 1967), and “The strong maximum principle revisited”, by Pucci and Serrin (review article, J. Differential Eq. **196**:1-66, 2004).