

# Symplectic forms

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## 1 Symplectic forms

We assume that the characteristic of our field is not 2 (so  $1 + 1 \neq 0$ ).

### 1.1 Definition and examples

Recall that a *skew-symmetric bilinear form* is a bilinear form  $\Omega$  such that  $\Omega(v, w) = -\Omega(w, v)$  for all  $v, w \in V$ . Note that if  $\Omega$  is a skew-symmetric bilinear form, then  $\Omega(v, v) = 0$  for all  $v \in V$ . In other words, every vector is isotropic.

A *symplectic form* is a non-degenerate skew-symmetric bilinear form. Recall that non-degenerate means that for all  $v \in V$  such that  $v \neq 0$ , there exists  $w \in V$  such that  $\Omega(v, w) \neq 0$ .

**Example 1.1.** Consider  $V = \mathbb{F}^2$  and take the bilinear form given by the matrix

$$\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

Here is a more general example. Let  $W$  be a vector space. Define a vector space  $V = W \oplus W^*$ . We define a bilinear form on  $V$  by the rule

$$\Omega((v_1, \alpha_1), (v_2, \alpha_2)) = \alpha_2(v_1) - \alpha_1(v_2)$$

This is clearly skew-symmetric. It is also non-degenerate since if  $(v_1, \alpha_1) \in V$  is non-zero, then either  $v_1 \neq 0$  or  $\alpha_1 \neq 0$ . Assume that  $v_1 \neq 0$ . Then we can choose  $\alpha_2 \in V^*$  such that  $\alpha_2(v_1) \neq 0$  and so  $\Omega((v_1, \alpha_1), (0, \alpha_2)) \neq 0$ . So  $\Omega$  is a symplectic form.

### 1.2 Symplectic bases

We cannot hope to diagonalize a symplectic form since every vector is isotropic. We will instead introduce a different goal.

Let  $V, \Omega$  be a vector space with a symplectic form. Suppose that  $\dim V = 2n$ . A *symplectic basis* for  $V$  is a basis  $q_1, \dots, q_n, p_1, \dots, p_n$  for  $V$  such that

$$\begin{aligned}\Omega(p_i, q_i) &= 1 \\ \Omega(q_i, p_i) &= -1 \\ \Omega(p_i, q_j) &= 0 \text{ if } i \neq j \\ \Omega(p_i, p_j) &= 0 \\ \Omega(q_i, q_j) &= 0\end{aligned}$$

In other words the matrix for  $\Omega$  with respect to this basis is the  $2n \times 2n$  matrix

$$\begin{bmatrix} 0_n & -I_n \\ I_n & 0_n \end{bmatrix}$$

**Theorem 1.2.** *Let  $V$  be a vector space and let  $\Omega$  be a symplectic form. Then  $\dim V$  is even and there exists a symplectic basis for  $V$ .*

*Proof.* We proceed by induction on  $\dim V$ . The base cases are  $\dim V = 0$  and  $\dim V = 1$ .

Now assume  $\dim V = n$  and assume the result holds for all vector spaces of dimension  $n - 2$ . Let  $q \in V$ ,  $q \neq 0$ . Since  $\Omega$  is non-degenerate, there exists  $p \in V$  such that  $\Omega(p, q) \neq 0$ . By scaling  $q$ , we can ensure that  $\Omega(p, q) = 1$ . Then  $\Omega(q, p) = -1$  by skew symmetry.

Let  $W = \text{span}(p, q)^\perp$ . So

$$W = \{v \in V : \Omega(v, p) = 0 \text{ and } \Omega(v, q) = 0\}.$$

We claim that  $W \cap \text{span}(p, q) = 0$ . Let  $v \in W \cap \text{span}(p, q)$ . Then  $v = ap + bq$  for some  $a, b \in \mathbb{F}$ . Since  $v \in W$ , we see that  $\Omega(v, p) = 0$ . But  $\Omega(v, p) = -b$ , so  $b = 0$ . Similarly,  $\Omega(v, q) = 0$ , which implies that  $a = 0$ . Hence  $v = 0$ .

Since  $\Omega$  is non-degenerate, we know that  $\dim W + \dim \text{span}(p, q) = \dim V$ . Thus  $W \oplus \text{span}(p, q) = V$ .

To apply the inductive hypothesis, we need to check now that the restriction of  $\Omega$  to  $W$  is a symplectic form. It is clearly skew-symmetric, so we just need to check that it is non-degenerate. To see this, pick  $w \in W$ ,  $w \neq 0$ . Then there exists  $v \in V$  such that  $\Omega(w, v) \neq 0$ . We can write  $w = u + u'$ , where  $u \in W$  and  $u' \in \text{span}(p, q)$ . By the definition of  $\text{span}(p, q)$ ,  $\Omega(u', w) = 0$ . Hence  $\Omega(u, w) \neq 0$  and so the restriction of  $\Omega$  to  $W$  is non-degenerate.

We now apply the inductive hypothesis to  $W$ . Note that  $\dim W = \dim V - 2$ . By the inductive hypothesis,  $\dim W$  is even and we have a symplectic basis  $q_1, \dots, q_m, p_1, \dots, p_m$  where  $2m = n - 2$ . Hence  $\dim V$  is even. We claim that  $q_1, \dots, q_m, q, p_1, \dots, p_m, p$  is a symplectic basis for  $W$ . This follows from the definitions.  $\square$

### 1.3 Lagrangians

Let  $V$  be a vector space of dimension  $2n$  and  $\Omega$  be a symplectic form on  $V$ . Recall that a subspace  $W$  of  $V$  is called *isotropic* if  $\Omega(w_1, w_2) = 0$  for all  $w_1, w_2 \in W$ . This is equivalent to the condition that  $W \subset W^\perp$ . Since  $\Omega$  is non-degenerate,  $\dim W^\perp + \dim W = \dim V$ . Hence the maximum possible dimension of an isotropic subspace is  $n$ . An isotropic subspace  $L$  of dimension  $n$  is called a *Lagrangian*.

**Example 1.3.** Let  $V$  be a 2 dimensional vector space. Then any 1-dimensional subspace is Lagrangian.

We can also produce Lagrangian subspaces from symplectic bases as follows.

**Proposition 1.4.** *Let  $q_1, \dots, q_n, p_1, \dots, p_n$  be a symplectic basis for  $V$ . Then  $\text{span}(q_1, \dots, q_n), \text{span}(p_1, \dots, p_n)$  are both Lagrangian subspaces of  $V$ .*

*Proof.* From the fact that  $\Omega(q_i, q_j) = 0$  for all  $i, j$ , we see that  $\Omega(v, w) = 0$  for all  $v, w \in \text{span}(q_1, \dots, q_n)$ . Hence  $\text{span}(q_1, \dots, q_n)$  is isotropic. Since it has dimension  $n$ , it is Lagrangian. The result for  $p_1, \dots, p_n$  is similar.  $\square$

Now suppose that  $V = W \oplus W^*$  for some vector space  $W$  and we define a symplectic form  $\Omega$  on  $W$  as above. Then it is easy to see that  $W$  and  $W^*$  are both Lagrangian subspaces of  $V$ .