

Full calculation for one example

$$A = \begin{pmatrix} 3 & 0 & 1 & -1 \\ 1 & 1 & 1 & -1 \\ 0 & -1 & 2 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix} \quad \lambda = 2, 2, 2, 2$$

① Seek eigenvectors.

Seek $V \neq \vec{0}$ so that $AV = 2V$

seek $V \neq 0$ so that $(A - 2I)V = 0$.

Solve

$$\begin{pmatrix} 1 & 0 & 1 & -1 \\ 1 & -1 & 1 & -1 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} V = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Write augmented matrix and do elementary row operations:

$$\left(\begin{array}{cccc|c} 1 & 0 & 1 & -1 & 0 \\ 1 & -1 & 1 & -1 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right) \rightarrow \left(\begin{array}{cccc|c} 1 & 0 & 1 & -1 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right) \rightarrow \left(\begin{array}{cccc|c} 1 & 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

elementary row operations don't change the solution set, so we seek solutions of

$$\begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \quad \begin{aligned} v_1 + v_3 - v_4 &= 0 \\ v_2 &= 0 \\ 0 &= 0 \\ 0 &= 0 \end{aligned}$$

(2)

v_3 and v_4 can be anything

$$v_4 = s \in \mathbb{R}$$

$$v_3 = t \in \mathbb{R}$$

$$v_2 = 0$$

$$v_1 = v_4 - v_3 = s - t$$

$$V = \begin{pmatrix} s-t \\ 0 \\ t \\ s \end{pmatrix} = s \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix} + t \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

2 linearly independent eigenvectors
are $v_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}$ and $v_2 = \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix}$.

(2) Try to solve $(A-2I)x = v_1$ and

$$(A-2I)x = v_2$$

Write augmented matrix

$$(A-2I | v_1 | v_2) \text{ and do}$$

the elementary row operations and
then extract the 2 simpler linear systems.

(3)

$$\left(\begin{array}{cccc|c|c} 1 & 0 & 1 & -1 & 1 & -1 \\ 1 & -1 & 1 & -1 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{array} \right) \Rightarrow \left(\begin{array}{cccc|c|c} 1 & 0 & 1 & -1 & 1 & -1 \\ 0 & -1 & 0 & 0 & -1 & 1 \\ 0 & -1 & 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{array} \right)$$

$$\downarrow$$

$$\left(\begin{array}{cccc|c|c} 1 & 0 & 1 & -1 & 1 & -1 \\ 0 & 1 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{array} \right)$$

So $(A-2I)x=V_1$ is equivalent to the

System $x_1 + x_3 - x_4 = 1$

$$x_2 = 1$$

$$0 = 1$$

$$0 = 1$$

No solution!

(we could have seen this from the beginning because row 4 of $A-2I$ is all zeros and the 4th component of $V_1 \neq 0$.)

$(A-2I)x=V_2$ is equivalent to the system

$$x_1 + x_3 - x_4 = -1$$

$$x_2 = -1$$

$$0 = 0$$

$$0 = 0$$

there are infinitely many solutions

$$x_4 = s \in \mathbb{R}$$

$$x_3 = t \in \mathbb{R}$$

$$x_2 = -1$$

$$x_1 = -1 - x_3 + x_4 = -1 - t + s$$

$(A - 2I)X = V_2$ has general solution

$$X = \begin{pmatrix} -1 - t + s \\ -1 \\ t \\ s \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \\ 0 \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix} + s \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} -1 \\ -1 \\ 0 \\ 0 \end{pmatrix} + tV_2 + sV_1$$

yes those are the eigenvectors. Not surprising they're there. Think it through! 😊

We only need one solution. So choose one

$$v_1 = \begin{pmatrix} -1 \\ -1 \\ 0 \\ 0 \end{pmatrix}$$

(5)

③ Solve $(A-2I)X=V_1$ or solve $(A-2I)^2 X=V_2$

The two problems are equivalent because $(A-2I)V_1=V_2$. But I'll do the first problem because I don't need to compute $(A-2I)^2$.

create augmented matrix $(A-2I|V_1)$

$$\left(\begin{array}{cccc|c} 1 & 0 & 1 & -1 & -1 \\ 1 & -1 & 1 & -1 & -1 \\ 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right) \rightarrow \left(\begin{array}{cccc|c} 1 & 0 & 1 & -1 & -1 \\ 0 & -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$$\downarrow$$

$$\left(\begin{array}{cccc|c} 1 & 0 & 1 & -1 & -1 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

So $(A-2I)X=V_1$ is equivalent to this linear system

$$\begin{aligned} x_1 + x_3 - x_4 &= -1 \\ x_2 &= 0 \\ 0 &= 0 \\ 0 &= 0 \end{aligned}$$

$$x_4 = s \in \mathbb{R}$$

$$x_3 = t \in \mathbb{R}$$

$$x_2 = 0$$

$$x_1 = -1 - x_3 + x_4 = -1 - t + s$$

$$\text{solution is } \begin{pmatrix} -1-t+s \\ 0 \\ t \\ s \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix} + s \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

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again the general solution of $(A-2I)x=v_1$ is of the form

$$\begin{pmatrix} -1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + tV_2 + sV_1$$

eigenvectors... no coincidence.

Need one solution, so choose one!

$$v_2 = \begin{pmatrix} -1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

ready to go! $P = (v_2 | v_1 | v_2 | v_1)$

$$= \begin{pmatrix} -1 & -1 & -1 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$P = \begin{pmatrix} -1 & -1 & -1 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$P^{-1} = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ -1 & 1 & -1 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$P^{-1}AP = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ -1 & 1 & -1 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 3 & 0 & 1 & -1 \\ 1 & 1 & 1 & -1 \\ 0 & -1 & 2 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} -1 & -1 & -1 & -1 \\ 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 2 & -1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 2 \\ 0 & 0 & 0 & 2 \end{pmatrix}$$

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Note: I found v_2 by solving $(A-2I)X = v_1$.

What if I'd found v_2 by solving

$$(A-2I)^2 X = v_2 = \begin{pmatrix} -1 \\ 0 \\ 0 \\ 0 \end{pmatrix} ?$$

$$(A-2I)^2 = \begin{pmatrix} 1 & -1 & 1 & -1 \\ 0 & 0 & 0 & 0 \\ -1 & 1 & -1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

build augmented matrix

$$\left(\begin{array}{cccc|c} 1 & -1 & 1 & -1 & -1 \\ 0 & 0 & 0 & 0 & 0 \\ -1 & 1 & -1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right) \rightarrow \left(\begin{array}{cccc|c} 1 & -1 & 1 & -1 & -1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

So

$$\begin{aligned} X_1 - X_2 + X_3 - X_4 &= -1 \\ 0 &= 0 \\ 0 &= 0 \\ 0 &= 0 \end{aligned}$$

is the linear system that's equivalent to $(A-2I)^2 = v_2$.

$$X_4 = s$$

$$X_3 = t$$

$$X_2 = r$$

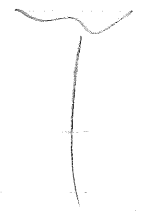
$$X_1 = -1 + r - t + s$$

Solution is

$$\begin{pmatrix} -1+r-t+s \\ r \\ t \\ s \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + r \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix} + s \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

that is $(A-2I)^2 X = V_2$ has general solution

$$\begin{pmatrix} -1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + r \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix} + s \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$



linear combination of eigenvectors, this is in $\ker(A-2I)$

in $\ker(A-2I)^2$ and is not in $\ker(A-2I)$

We need only one solution to choose V_2 and build the matrix P but we see that there are infinitely many choices determined up to the kernel of $(A-2I)^2$.

$A-2I$ has rank 2 $\Rightarrow \dim(\ker(A-2I)) = 2$
 $\Rightarrow 2$ eigenvectors & 2 jordan blocks.

$$(A-2I)^2 = \begin{pmatrix} 1 & -1 & 1 & -1 \\ 0 & 0 & 0 & 0 \\ -1 & 1 & -1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \text{ has rank } 1$$

$\Rightarrow \dim(\ker(A-2I)^3) = 3$
 $\Rightarrow \exists 1$ jordan block of size > 1 .
 \uparrow 1 because $3-2=1$

$(A - 2I)^3 = \text{zero matrix}$ has rank 0

$$\Rightarrow \dim(\ker((A - 2I)^3)) = 4$$

$\Rightarrow \exists$ 1 jordan block of size > 2

\uparrow
1 because $4 - 3 = 1$.

2 jordan blocks in a 4×4 matrix and one of them has size > 2 . Only one possibility:

$$A \sim \begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 2 \end{pmatrix}$$

All of this numerology is fine and good but it doesn't help in constructing P so that

$$A = P \begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 2 \end{pmatrix} P^{-1}$$



Sometimes, things get a little tricky though!

In the previous example, I sought X so that

$$(A - 2I)X = V_1 \text{ or } (A - 2I)X = V_2$$

Being able to solve this required that V_1 or V_2 is in the range of $(A - 2I)$.

But what if they aren't?

For example,

$$A = \begin{pmatrix} -10 & -5 & -11 & 16 \\ -6 & -5 & -9 & 12 \\ 0 & 0 & -2 & 0 \\ -7 & -4 & -10 & 12 \end{pmatrix}$$

The eigenvalues of A are $1, -2, -2, -2$

$$E_1 = \text{span} \left\{ \begin{pmatrix} 13 \\ -1 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$$E_{-2} = \text{span} \left\{ \begin{pmatrix} -2 \\ 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} \right\}$$

We need to find a vector U so that

$(A - (-2)I)U$ is an eigenvector w/
eigenvalue -2

if we try to solve

$$(A - (-2)I)X = \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}$$

we find there's no solution. If we try to solve

$$(A - (-2)I)X = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$$

we find there's no solution.

This is because

$$\begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix} \notin \text{range}(A - (-2)I)$$

$$\begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \notin \text{range}(A - (-2)I)$$

we need to find an eigenvector

that is in the range of $A - (-2)I$

i.e. find α and β so that

$$\alpha \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix} + \beta \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \in \text{range}(A - (-2)I)$$

$$(A - (-2)I) = \begin{pmatrix} -8 & -5 & -11 & 16 \\ -6 & -3 & -9 & 12 \\ 0 & 0 & 0 & 0 \\ -7 & -4 & -10 & 14 \end{pmatrix}$$

Has reduced row echelon form

$$\begin{pmatrix} 1 & 0 & 2 & -2 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

\Rightarrow the range of $A - (-2I)$ is spanned by the first 2 columns of $A - (-2I)$

$$\text{range}(A - (-2I)) = \text{span} \left\{ \begin{pmatrix} -8 \\ -6 \\ 0 \\ -7 \end{pmatrix}, \begin{pmatrix} 5 \\ -3 \\ 0 \\ -4 \end{pmatrix} \right\}$$

So I seek α, β so that

$$\alpha \begin{pmatrix} -2 \\ 1 \\ 1 \\ 0 \end{pmatrix} + \beta \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} \in \text{span} \left\{ \begin{pmatrix} -8 \\ -6 \\ 0 \\ -7 \end{pmatrix}, \begin{pmatrix} 5 \\ -3 \\ 0 \\ -4 \end{pmatrix} \right\}$$

$$\begin{pmatrix} -8 & -5 & -2 & 0 \\ -6 & -3 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ -7 & -4 & 0 & 1 \end{pmatrix} \text{ has RREF } \begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\Rightarrow -1 \begin{pmatrix} -2 \\ 1 \\ 1 \\ 0 \end{pmatrix} + 1 \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} = 1 \begin{pmatrix} -8 \\ -6 \\ 0 \\ -7 \end{pmatrix} - 2 \begin{pmatrix} 5 \\ -3 \\ 0 \\ -4 \end{pmatrix}$$

this is an eigenvector that is in the range of $A - (-2)I$

So we choose a new basis for our eigen space

$$E_{-2} \text{ span } \left\{ \begin{pmatrix} 2 \\ 0 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} \right\}$$

↑

is in Range $A - (-2)I$

$$\left(\begin{array}{cccc|c|c} -8 & -5 & -11 & 16 & 2 & 0 \\ -6 & -3 & -9 & 12 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ -7 & -4 & -10 & 14 & 1 & 1 \end{array} \right)$$

$$\text{has RREF } \left(\begin{array}{cccc|c|c} 1 & 0 & 2 & -2 & 1 & 0 \\ 0 & 1 & -1 & 0 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

So we get

$$x_1 + 2x_3 - 2x_4 = 1$$

$$x_2 - x_3 = -2$$

$$x_4 = t$$

$$x_3 = s$$

$$x_2 = -2 + s$$

$$x_1 = 1 - 2s + 2t$$

$$\vec{u} = \begin{pmatrix} 1 \\ -2 \\ 0 \\ 0 \end{pmatrix} + s \begin{pmatrix} -2 \\ 1 \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} 2 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

eigenvectors

only need one choice for \vec{u} so

take
$$\vec{u} = \begin{pmatrix} 1 \\ -2 \\ 0 \\ 0 \end{pmatrix}.$$

$$P = \begin{pmatrix} 1 & 2 & 1 & 0 \\ 1 & 0 & 2 & 1 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 0 & 1 \end{pmatrix} \quad J = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -2 & 1 & 0 \\ 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & -2 \end{pmatrix}$$

$$P^{-1} = \begin{pmatrix} -2 & -1 & -3 & 4 \\ 2 & 1 & 2 & -3 \\ -1 & -1 & -1 & 2 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

done!