

# MAT 351: Partial Differential Equations

## Assignment 18, due March 27, 2017

### Summary:

- A **test function** on a domain  $D \subset \mathbb{R}^d$  is a smooth function with compact support in  $D$ .

The space of test functions on  $\mathbb{R}^d$  will be denoted by  $\mathcal{D}$ . We say that  $\lim \phi_j = \phi$  in  $\mathcal{D}$ , if (i) the functions are supported on a common compact set  $K \subset \mathbb{R}^d$ , (ii) the functions converge uniformly to  $\phi$ , and (iii) all their derivatives converge uniformly as well.

- A **distribution** is a linear transformation mapping test functions to  $\mathbb{R}$  (or  $\mathbb{C}$ ).

In other words, a distribution  $f$  assigns to each  $\phi \in \mathcal{D}$  a scalar  $f(\phi)$ . We require that this transformation be **continuous** on  $\mathcal{D}$ , in the sense that

$$\lim \phi_j = \phi \quad \Rightarrow \quad \lim f(\phi_j) = f(\phi).$$

We denote the space of distributions by  $\mathcal{D}'$ , and think of it as the dual space of  $\mathcal{D}$ .

- A sequence of distributions  $\{f_j\}$  **converges weakly** to  $f$ , if  $\lim f_j(\phi) = f(\phi)$  for all  $\phi \in \mathcal{D}$ .

Functions are important special cases of distributions. If  $f$  is a continuous function on  $\mathbb{R}^d$ , we can define the corresponding distribution by

$$f(\phi) = \int f(x)\phi(x) dx.$$

We often write distributions in this form, even when they are not given by a function. For example, the Dirac  $\delta$ -distribution is defined by

$$\delta(\phi) = \int \phi(x)\delta(x) dx := \phi(0).$$

The  $\delta$ -distribution on  $\mathbb{R}^d$  can be obtained as the weak limit of a **Dirac sequence**  $\varepsilon^{-d}f(\varepsilon^{-1}x)$ , where  $f$  is a nonnegative integrable function with  $\int f(x) dx = 1$ , and  $\varepsilon \rightarrow 0^+$ .

- **Distributional derivatives** of  $f$  are defined by  $(D_i f)(\phi) = -f(\frac{\partial}{\partial x_i} \phi)$  for all test functions  $\phi$ .

Distributional derivatives are also called **weak derivatives**. If  $f$  is given by a differentiable function, then its distributional derivatives are given by the classical derivatives of  $f$ . To give another example, the derivative of the  $\delta$ -distribution in one dimension is defined by  $\delta'(\phi) = -\phi'(0)$ .

When solving a linear PDE  $Lu = 0$ , it is often useful to consider distributional solutions. For example, the fundamental solution of Laplace's equation  $\Delta u = f$  on  $\mathbb{R}^d$ , given by

$$G_0(x) = C_d |x|^{2-d},$$

(where  $C_d$  is a specific dimension-dependent constant) solves

$$-\Delta u = \delta$$

in the sense of distributions. In this case, both  $G_0$  and its gradient  $\nabla G_0$  turn out to be functions. But note that distributional solutions make no sense for nonlinear equations, because a nonlinear function of a distribution is not a distribution. (For example,  $\delta^2$  has no meaning.)

## Assignments:

Read the first two sections of Chapter 12 of Strauss.

73. Compute the first three distributional derivatives of the function

$$f(x) = \max\{0, 1 - x^2\}.$$

74. Let  $f$  be a distribution on  $\mathbb{R}$  with  $f' = 0$ .

- (a) What does that mean?
- (b) Prove that  $f(\phi) = 0$  for all test functions  $\phi$  with  $\int_{\mathbb{R}} \phi(x) dx = 0$ .
- (c) Conclude that  $f$  is given by a constant function  $f(x) = c$ , by showing that

$$f(\phi) = c \int_{\mathbb{R}} \phi(x) dx$$

for all test function  $\phi$ . (*Hint: First consider the case where  $\int_{\mathbb{R}} \phi(x) dx = 0$ .)*

75. Consider **Burger's equation**

$$u_t + uu_x = 0, \quad u(x, 0) = u_0(x) \tag{1}$$

for  $x \in \mathbb{R}$  and  $t > 0$ . A **integral solution** of the equation is a function  $u$  such that

$$\int_0^\infty \int_{-\infty}^\infty u\phi_t + \frac{1}{2}u^2\phi_x dxdt + \int_{-\infty}^\infty u_0(x)\phi(0, x) dx \tag{2}$$

holds for every smooth test function  $\phi(x, t)$  with compact support in  $\mathbb{R} \times [0, \infty)$ . (Note that  $\phi$  need not vanish on the line  $t = 0$ .)

- (a) Suppose  $u$  itself is smooth. Verify that then Eq. (2) and Eq. (1) are equivalent.
- (b) Let  $u$  be a smooth solution of Burger's equation. Assume that, for each  $t \geq 0$ ,  $u(\cdot, t)$  has compact support, and define its **mass** by

$$M(t) = \int_{-\infty}^\infty u(x, t) dx.$$

Prove that mass is conserved, i.e.,  $M(t)$  is constant in time. (*Hint: Compute  $\frac{d}{dt}M(t)$ .)*

- (c) Suppose  $u$  is a continuous integral solution of Burger's equation, i.e.,  $u$  satisfies Eq. (2). Assume furthermore that  $u(\cdot, t)$  has compact support for each  $t \geq 0$ . Show that mass is conserved also in this case. (*Hint: Use test functions of the form  $\phi(x, t) = a(x)b(t)$ .)*