

The Hardest Math I've Ever Really Used, 1

Dror Bar-Natan at the CMS Niagara Falls Meeting
<http://drorbn.net/n16>
 December 2016

Abstract. What's the hardest math I've ever used in real life? Me, myself, directly - not by using a cellphone or a GPS device that somebody else designed? And in "real life" — not while studying or teaching mathematics? I use addition and subtraction daily, adding up bills or calculating change. I use percentages often, though mostly it is just "add 15 percents". I seldom use multiplication and division: when I buy in bulk, or when I need to know how many tiles I need to replace my kitchen floor. I've used powers twice in my life, doing calculations related to mortgages. I've used a tiny bit of geometry and algebra for a tiny bit of non-math-related computer graphics I've played with. And for a long time, that was all. In my talk I will tell you how recently a math topic discovered only in the 1800s made a brief and modest appearance in my non-mathematical life. There are many books devoted to that topic and a lot of active research. Yet for all I know, nobody ever needed the actual formulas for such a simple reason before. Hence we'll talk about the motion of movie cameras, and the fastest way to go from A to B subject to driving speed limits that depend on the locale, and the "happy segway principle" which is at the heart of the least action principle which in itself is at the heart of all of modern physics, and finally, about that funny discovery of Janos Bolyai's and Nikolai Ivanovich Lobachevsky's, that the famed axiom of parallels of the ancient Greeks need not actually be true.

Dror Bar-Natan: Talks Mathcamp-0907:

The Problem. Let $G = (g_1, \dots, g_n)$ be a subgroup of S_n , with $n = O(100)$. Before you die, understand G :

1. Compute $|G|$.
2. Given $\sigma \in S_n$, decide if $\sigma \in G$.
3. Write a $\sigma \in G$ in terms of g_1, \dots, g_n .
4. Produce random elements of G .

The Commutative Analog. Let $V = \text{span}(v_1, \dots, v_n)$ be a subspace of \mathbb{R}^n . Before you die, understand V .

Solution: Gaussian Elimination. Prepare an empty table.

1	2	3	4	...	n-1	n
---	---	---	---	-----	-----	---

Space for a vector $u_i \in V$, of the form $u_i = (0, 0, 1, *, \dots, *)$; 1 := "the pivot".

Feed v_1, \dots, v_n in order. To feed a non-zero v , find its pivotal position i .

1. If box i is empty, put v there.
2. If box i is occupied, find a combination v' of v and u_i that eliminates the pivot, and feed v' .

Non-Commutative Gaussian Elimination
 Prepare a mostly-empty table.

$\begin{pmatrix} 1,1 \\ 1 \end{pmatrix}$	$\begin{pmatrix} 1,2 \\ 2 \end{pmatrix}$	$\begin{pmatrix} 1,3 \\ 3 \end{pmatrix}$	$\begin{pmatrix} 1,4 \\ 4 \end{pmatrix}$...	$\begin{pmatrix} 1,n \\ n \end{pmatrix}$
--	--	--	--	-----	--

Space for a $\sigma_{i,j} \in S_n$ of the form $(1, 2, \dots, i-2, i-1, j, *, \dots, *)$
 So $\sigma_{i,j}$ fixes $1, \dots, i-1$, sends "the pivot" i to j and goes wild afterwards, and $\sigma_{i,j}^{-1}$ "does sticker j ".

Feed g_1, \dots, g_n in order. To feed a non-identity σ , find its pivotal position i and let $j := \sigma(i)$.

1. If box (i, j) is empty, put σ there.
2. If box (i, j) contains $\sigma_{i,j}$, feed $\sigma' := \sigma_{i,j}^{-1}\sigma$.

The Twist. When done, for every occupied (i, j) and (k, l) , feed $\sigma_{i,j}\sigma_{k,l}$. Repeat until the table stops changing.

Claim. The process stops in our lifetimes, after at most $O(n^6)$ operations. Call the resulting table T .

Claim. Anything fed in T is a monotone product in T :
 f was fed $\Rightarrow f \in M_1 := \{\sigma_{i_1 j_1} \sigma_{i_2 j_2} \dots \sigma_{i_n j_n} : \forall i, j_i \geq i \ \& \ \sigma_{i_i j_i} \in T\}$

Homework Problem 1. Can you do cosets?

Homework Problem 2. Can you do categories (groupoids)?

The Results
 $\text{In}[3] := (\text{Feed}[T]; \text{Product}[1 + \text{Length}[\text{Select}[\text{Range}[n], \text{Head}[s[i, \#]] == \# \&]], \{i, n\}]) \& / \& \text{g}$
 $\text{Out}[3] := \{4, 16, 159993501696000, 21119142223872000, 43252003274489856000, 43252003274489856000\}$
<http://www.math.toronto.edu/~drorbn/Talks/Mathcamp-0907/> and links there

Non-Commutative Gaussian Elimination and Rubik's Cube

The Generators
 $\text{In}[1] := \text{gs} = \{$
 purple = $P[18, 27, 36, 4, 5, 6, 7, 8, 9, 3, 11, 12, 13, 14, 15, 16, 17, 45, 2, 20, 21, 22, 23, 24, 25, 26, 44, 1, 29, 30, 31, 32, 33, 34, 35, 43, 37, 38, 39, 40, 41, 42, 10, 19, 28, 52, 49, 46, 53, 50, 47, 54, 51, 48],$
 white = $P[1, 2, 3, 4, 5, 6, 16, 25, 34, 10, 11, 9, 15, 24, 33, 39, 17, 18, 19, 20, 8, 14, 23, 32, 38, 26, 27, 28, 29, 7, 13, 22, 31, 37, 35, 36, 12, 21, 30, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54],$
 green = $P[1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 31, 32, 33, 34, 35, 36, 48, 47, 46, 39, 42, 45, 38, 41, 44, 37, 40, 43, 30, 29, 28, 49, 50, 51, 52, 53, 54],$
 blue = $P[18, 9, 2, 5, 8, 1, 4, 7, 54, 53, 52, 10, 11, 12, 13, 14, 15, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 18, 17, 16],$
 red = $P[13, 2, 3, 22, 5, 6, 31, 8, 9, 12, 21, 30, 37, 14, 15, 16, 17, 19, 11, 20, 29, 40, 23, 24, 25, 26, 27, 10, 19, 28, 49, 32, 33, 34, 35, 36, 46, 38, 39, 49, 41, 42, 52, 44, 45, 1, 47, 48, 4, 50, 51, 7, 53, 54],$
 yellow = $P[1, 2, 48, 4, 5, 51, 7, 8, 54, 10, 11, 12, 13, 14, 3, 18, 27, 36, 19, 20, 21, 22, 23, 6, 17, 26, 35, 28, 29, 30, 31, 32, 9, 16, 25, 34, 37, 38, 15, 40, 41, 24, 43, 44, 33, 46, 47, 39, 49, 50, 42, 52, 53, 45],$
 $\} ;$ **Enter**

Theorem. $G = M_1$.
 $G = M_1 := \{\sigma_{i_1 j_1} \sigma_{i_2 j_2} \dots \sigma_{i_n j_n} : \forall i, j_i \geq i \ \& \ \sigma_{i_i j_i} \in T\}$
Proof. The inclusions $M_1 \subset G$ and $\{g_1, \dots, g_n\} \subset M_1$ are obvious. The rest follows from the following **Lemma.** M_1 is closed under multiplication.
Proof. By backwards induction. Let
 $M_k := \{\sigma_{k,j_k} \dots \sigma_{n,j_n} : \forall i \geq k, j_i \geq i \ \& \ \sigma_{i_i j_i} \in T\}$.
 Clearly $M_n \subset M_{n-1}$. Now assume that $M_5 M_6 \subset M_5$ and show that $M_4 M_5 \subset M_4$. Start with $\sigma_{k,j_k} M_4 \subset M_4$:
 $\sigma_{k,j_k} (\sigma_{i_1 j_1} M_5) \stackrel{1}{=} (\sigma_{k,j_k} \sigma_{i_1 j_1}) M_5 \stackrel{2}{=} M_4 M_5$
 $\stackrel{3}{=} \sigma_{k,j_k} (M_5 M_6) \stackrel{4}{=} \sigma_{k,j_k} M_5 \subset M_4$
 (1: associativity, 2: thank the twist, 3: associativity and tracing i_1 , 4: induction). Now the general case $(\sigma_{k,j_k} \sigma_{i_1 j_1} \dots) (\sigma_{i_1 j_1} \sigma_{i_2 j_2} \dots)$ falls like a chain of dominos.

Problem Solved!

A Demo Program

```

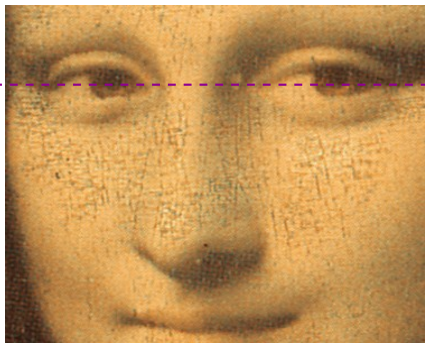
1 In[2]:= (ResourceLimit = 2^16;
2 n = 64;
3 P := p.p ** P[a....] := p[{a...}];
4 Invp[p] := P @@ Ordering[p];
5 Feed[P @ Range[n]] := Null;
6 Feed[p.P] := Module[{i, j},
7   For[i = 1, p[{i}] == i, ++i];
8   j = p[{i}];
9   If[Head[i, j]] == P,
10    Feed[Invp[i, j]] ** p,
11    (* Else *) s[i, j] = p;
12    Do[If[Head[s[k, l]] == P,
13      Feed[s[k, l]] ** s[i, j]],
14      {k, n}, {l, n}];
15 ];]; Enter
```

that's cool!

$\text{In}[3] := (\text{Feed}[T]; \text{Product}[1 + \text{Length}[\text{Select}[\text{Range}[n], \text{Head}[s[i, \#]] == \# \&]], \{i, n\}]) \& / \& \text{g}$
 $\text{Out}[3] := \{4, 16, 159993501696000, 21119142223872000, 43252003274489856000, 43252003274489856000\}$
<http://drorbn.net/n16>

I could be a mathematician ...

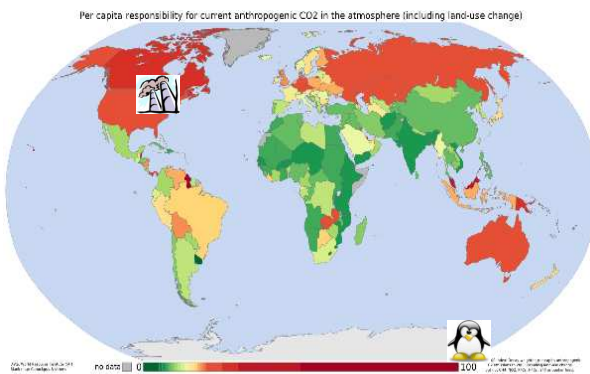
...or an art historian...



...or an environmentalist.



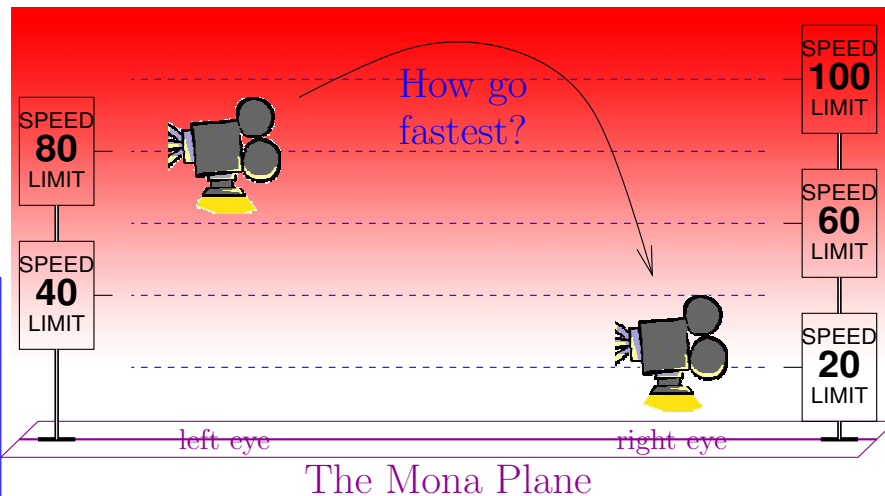
Al Gore in Futurama, circa 3000AD



Goal. Find the least-blur path to go from Mona's left eye to Mona's right eye in fixed time. Alternatively, fix your blur-tolerance, and find the fastest path to do the same. For fixed blur, our camera moves at a speed proportional to its distance from the image plane:



<http://drorbn.net/n16>



Video at <http://www.math.toronto.edu/~drorbn/Talks/RCI-110213/>, more at <http://www.math.toronto.edu/~drorbn/Talks/Niagara-1612/>