University of Toronto Solutions to MAT188H1F TERM TEST of Tuesday, November 9, 2010 Duration: 100 minutes

General Comments about the Test:

1. Lots of students are still using incorrect notation

 \Rightarrow instead of \rightarrow , = instead of \rightarrow , etc

or even worse, are equating a matrix to a determinant, or a transformation to a matrix, or a determinant to a vector, etc. If you keep doing it, we'll keep taking marks off.

2. Rational and irrational numbers are not the same things. What your calculator gives you is by default a rational number. So (from Question 3)

$$\frac{8}{\sqrt{59}} \neq 1.04$$

One is an *approximation* of the other, so don't put equal signs between them. Respect equality!

- 3. For Question 7: use properties of determinants to ease the calculation of $det(\lambda I A)$. If you simply expand the determinant and get a cubic, then you have to factor it-and that might not be easy.
- 4. Many students need to explain their work; every time a marker has to figure out what you are doing it costs you marks.

Breakdown of Results: 950 students wrote this test. The marks ranged from 7% to 100%, and the average was 74.4%. Some statistics on grade distributions are in the table on the left, and a histogram of the marks (by decade) is on the right.

Grade	%	Decade	%
		90-100%	18.0%
A	43.2%	80-89%	25.2%
В	23.6~%	70-79%	23.6%
C	17.5%	60-69%	17.5~%
D	8.8%	50-59%	8.8~%
F	6.9%	40-49%	4.2%
		30-39%	1.5%
		20-29%	0.6%
		10-19%	0.5%
		0-9%	0.1%



1. [8 marks] Find the reduced row-echelon form of the matrix

$$A = \begin{bmatrix} 1 & 2 & 1 & 0 & 3\\ 3 & 6 & 5 & -2 & 13\\ -2 & -4 & -2 & 0 & -8\\ -1 & -2 & 1 & -2 & 2 \end{bmatrix}$$

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What is the rank of A?

Solution:

$$\begin{bmatrix} 1 & 2 & 1 & 0 & 3 \\ 3 & 6 & 5 & -2 & 13 \\ -2 & -4 & -2 & 0 & -8 \\ -1 & -2 & 1 & -2 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 1 & 0 & 3 \\ 0 & 0 & 2 & -2 & 4 \\ 0 & 0 & 0 & 0 & -2 \\ 0 & 0 & 2 & -2 & 5 \end{bmatrix}$$
$$\rightarrow \begin{bmatrix} 1 & 2 & 1 & 0 & 3 \\ 0 & 0 & 1 & -1 & 2 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$
$$\rightarrow \begin{bmatrix} 1 & 2 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$
$$\rightarrow \begin{bmatrix} 1 & 2 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$
$$\rightarrow \begin{bmatrix} 1 & 2 & 0 & 1 & 0 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

The rank of A is the number of leading 1's in the reduced row-echelon matrix; so the rank is 3.

Note: The reduced row-echelon form of a matrix is unique; there is only one correct answer.

- 2. [9 marks] Consider the three points in space: A(1, 1, 1), B(2, 3, -5), C(0, 2, 2).
 - (a) [5 marks] Find the scalar equation of the plane passing through the three points A, B and C.

Solution: Let
$$\vec{u} = \overrightarrow{AB} = \begin{bmatrix} 1\\ 2\\ -6 \end{bmatrix}$$
 and $\vec{v} = \overrightarrow{AC} = \begin{bmatrix} -1\\ 1\\ 1 \end{bmatrix}$.

Then a normal vector to the plane is given by

$$\vec{n} = \vec{u} \times \vec{v} = \begin{bmatrix} 1\\ 2\\ -6 \end{bmatrix} \times \begin{bmatrix} -1\\ 1\\ 1 \end{bmatrix}$$
$$= \begin{bmatrix} 8\\ 5\\ 3 \end{bmatrix};$$

and using the point C, the scalar equation of the plane is

$$\vec{n} \cdot \begin{bmatrix} x-0\\y-2\\z-2 \end{bmatrix} = 0 \Leftrightarrow 8x + 5y + 3z = 16.$$

Alternates: You could just as well take

$$\vec{n} = \overrightarrow{BA} \times \overrightarrow{BC} = \begin{bmatrix} -8\\ -5\\ -3 \end{bmatrix}$$

or

$$\vec{n} = \overrightarrow{CB} \times \overrightarrow{CA} = \begin{bmatrix} -8\\ -5\\ -3 \end{bmatrix}$$

and you could use either of the given points, A, B or C.

(b) [4 marks] What is the area of the triangle with vertices A, B and C?

Solution: area
$$=\frac{1}{2} \| \vec{u} \times \vec{v} \| = \frac{1}{2} \sqrt{8^2 + 5^2 + 3^2} = \frac{\sqrt{98}}{2} = \frac{7}{\sqrt{2}}.$$

3. [9 marks] Find the minimum distance between the skew lines \mathbb{L}_1 and \mathbb{L}_2 if their parametric equations are

$$\mathbb{L}_1: \left\{ \begin{array}{rrrr} x &= 4 &- 2t \\ y &= 2 &+ t \\ z &= 1 &+ t \end{array} \right. \text{ and } \mathbb{L}_2: \left\{ \begin{array}{rrrr} x &= 2 &+ 3s \\ y &= 2 &- s \\ z &= 3 &+ 2s \end{array} \right.$$

where s and t are parameters.

Solution: The line \mathbb{L}_1 passes through the point P(4,2,1) with direction vector

$$\vec{d_1} = \begin{bmatrix} -2\\1\\1 \end{bmatrix};$$

the line \mathbb{L}_2 passes through the point Q(2,2,3) with direction vector

$$\vec{d_2} = \begin{bmatrix} 3\\-1\\2 \end{bmatrix}.$$

A vector orthogonal to both lines is

$$\vec{n} = \vec{d_1} \times \vec{d_2} = \begin{bmatrix} -2\\1\\1 \end{bmatrix} \times \begin{bmatrix} 3\\-1\\2 \end{bmatrix} = \begin{bmatrix} 3\\7\\-1 \end{bmatrix}.$$

Then the minimum distance between the two skew lines is given by

$$\|\operatorname{proj}_{\vec{n}} \overrightarrow{PQ}\| = \frac{|\vec{n} \cdot P\dot{Q}|}{\|\vec{n}\|} = \frac{|(3)(-2) + (7)(0) + (-1)(2)|}{\sqrt{9 + 49 + 1}} = \frac{|-8|}{\sqrt{59}} = \frac{8}{\sqrt{59}}$$

Alternate Solution: this is longer, but you could actually find the two points that are closest together. Let

$$\vec{z} = \begin{bmatrix} -2+3s+2t \\ -s-t \\ 2+2s-t \end{bmatrix}$$

be the general vector from a point on \mathbb{L}_1 to a point on \mathbb{L}_2 . Then solve $\vec{z} \cdot \vec{d_1} = 0$ and $\vec{z} \cdot \vec{d_2} = 0$, or equivalently $\vec{z} \times \vec{n} = \vec{0}$, to find s = -18/59, t = 74/59. Then the minimum distance between the two lines is

$$\|\vec{z}\| = \left\| \begin{bmatrix} -24/59\\ -56/59\\ 8/59 \end{bmatrix} \right\| = \frac{\sqrt{3776}}{59} = \frac{8}{\sqrt{59}}.$$

4. [9 marks] Compute the following:

(a)
$$[5 \text{ marks}] \det \begin{bmatrix} 1 & 0 & -1 & 1 \\ 2 & 4 & 0 & 4 \\ -1 & 2 & 1 & 3 \\ 5 & 3 & 0 & 1 \end{bmatrix}$$

Solution: use properties of determinants to simplify your work.

$$\det \begin{bmatrix} 1 & 0 & -1 & 1 \\ 2 & 4 & 0 & 4 \\ -1 & 2 & 1 & 3 \\ 5 & 3 & 0 & 1 \end{bmatrix} = \det \begin{bmatrix} 1 & 0 & -1 & 1 \\ 2 & 4 & 0 & 4 \\ 0 & 2 & 0 & 4 \\ 5 & 3 & 0 & 1 \end{bmatrix} = (-1)(-1)^4 \det \begin{bmatrix} 2 & 4 & 4 \\ 0 & 2 & 4 \\ 5 & 3 & 1 \end{bmatrix}$$
$$= (-1)(2)(2) \det \begin{bmatrix} 1 & 2 & 2 \\ 0 & 1 & 2 \\ 5 & 3 & 1 \end{bmatrix} = -4(1+20+0-10-0-6) = -20.$$
(b) [4 marks]
$$\begin{bmatrix} 1 & 1 & 2 \\ 0 & 7 & 2 \\ 2 & -1 & 3 \end{bmatrix}^{-1}$$

Solution: this solution uses the Gaussian algorithm.

$$\begin{bmatrix} 1 & 1 & 2 & | & 1 & 0 & 0 \\ 0 & 7 & 2 & | & 0 & 1 & 0 \\ 2 & -1 & 3 & | & 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 2 & | & 1 & 0 & 0 \\ 0 & 7 & 2 & | & 0 & 1 & 0 \\ 0 & -3 & -1 & | & -2 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 2 & | & 1 & 0 & 0 \\ 0 & 7 & 2 & | & 0 & 1 & 0 \\ 0 & 0 & -1 & | & -14 & 3 & 7 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 1 & 0 & | & -27 & 6 & 14 \\ 0 & 7 & 0 & | & -28 & 7 & 14 \\ 0 & 0 & 1 & | & 14 & -3 & -7 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & | & -23 & 5 & 12 \\ 0 & 1 & 0 & | & -4 & 1 & 2 \\ 0 & 0 & 1 & | & 14 & -3 & -7 \end{bmatrix}$$

So

$$\begin{bmatrix} 1 & 1 & 2 \\ 0 & 7 & 2 \\ 2 & -1 & 3 \end{bmatrix}^{-1} = \begin{bmatrix} -23 & 5 & 12 \\ -4 & 1 & 2 \\ 14 & -3 & -7 \end{bmatrix}.$$

Alternate Solution: use the adjoint formula:

$$A^{-1} = \frac{\operatorname{adj}(A)}{\operatorname{det}(A)} = \frac{[C_{ij}]^T}{(-1)} = (-1) \begin{bmatrix} 23 & 4 & -14 \\ -5 & -1 & 3 \\ -12 & -2 & 7 \end{bmatrix}^T = \begin{bmatrix} -23 & 5 & 12 \\ -4 & 1 & 2 \\ 14 & -3 & -7 \end{bmatrix}.$$

5. [8 marks] Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be the transformation defined by the formula

$$T\left(\left[\begin{array}{c}x\\y\end{array}\right]\right) = \left[\begin{array}{c}2x+4y\\x+3y\end{array}\right].$$

(a) [4 marks] Sketch the image of the unit square.

Solution:

$$T(\vec{i}) = T\left(\begin{bmatrix} 1\\0 \end{bmatrix}\right) = \begin{bmatrix} 2\\1 \end{bmatrix} \text{ and } T(\vec{j}) = T\left(\begin{bmatrix} 0\\1 \end{bmatrix}\right) = \begin{bmatrix} 4\\3 \end{bmatrix}.$$

So the image of the unit square is
the parallelogram determined by
$$\begin{bmatrix} 2\\1 \end{bmatrix} \text{ and } \begin{bmatrix} 4\\3 \end{bmatrix}.$$

(b) [4 marks] Find the formula for $T^{-1}\left(\begin{bmatrix} x \\ y \end{bmatrix}\right)$.

Solution: The matrix of T is

$$A = [T(\vec{i})|T(\vec{j})] = \begin{bmatrix} 2 & 4\\ 1 & 3 \end{bmatrix}.$$

Then the matrix of T^{-1} is

$$A^{-1} = \frac{1}{2} \begin{bmatrix} 3 & -4 \\ -1 & 2 \end{bmatrix},$$

and the formula for T^{-1} is

$$T^{-1}\left(\left[\begin{array}{c}x\\y\end{array}\right]\right) = \frac{1}{2}\left[\begin{array}{c}3&-4\\-1&2\end{array}\right]\left[\begin{array}{c}x\\y\end{array}\right]$$
$$= \frac{1}{2}\left[\begin{array}{c}3x-4y\\-x+2y\end{array}\right]$$

6. [8 marks] Let $S : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ be the projection on the line with equation y = -2x, induced by the matrix A; let $T : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ be the projection on the line with equation y = x/2, induced by the matrix B. Compute both AB and BA. Interpret your results geometrically.

Solution: a projection on the line y = mx has matrix

$$\frac{1}{1+m^2} \left[\begin{array}{cc} 1 & m \\ m & m^2 \end{array} \right]$$

So with m = -2,

$$A = \frac{1}{5} \begin{bmatrix} 1 & -2\\ -2 & 4 \end{bmatrix}$$

and with m = 1/2,

$$B = \frac{1}{1+1/4} \begin{bmatrix} 1 & 1/2 \\ 1/2 & 1/4 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix}.$$

Then

and

$$AB = \frac{1}{25} \begin{bmatrix} 1 & -2 \\ -2 & 4 \end{bmatrix} \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$
$$BA = \frac{1}{25} \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & -2 \\ -2 & 4 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}.$$

Geometric Interpretation:

The lines y = -2x and y = x/2 are orthogonal to each other. For any vector \vec{v} , $A(\vec{v})$ is parallel to the line y = -2x, and $B(\vec{v})$ is parallel to the line y = x/2. Thus: $A(\vec{v})$ is orthogonal to the line y = x/2, and B(v) is orthogonal to the line y = -2x.

Hence, for all vectors \vec{v} ,

$$B(A(\vec{v})) = \vec{0}$$
 and $A(B(\vec{v})) = \vec{0}$.



This means the two matrices, BA, and AB, are both the zero matrix. Or putting it another way: Let $\vec{v} \in \mathbb{R}^2$; let $\vec{d_1} = [1 \ -2]^T$ and let $\vec{d_2} = [2 \ 1]^T$. Then $\vec{d_1} \cdot \vec{d_2} = 0$ and

$$(AB)(\vec{v}) = S(T(\vec{v})) = S\left(\operatorname{proj}_{\vec{d_2}}\vec{v}\right) = \operatorname{proj}_{\vec{d_1}}\left(\operatorname{proj}_{\vec{d_2}}\vec{v}\right) = \vec{0},$$

so AB = O. Similarly, BA = O.

7. [10 marks] Find the eigenvalues and eigenvectors of $A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$ and determine if A is diagonalizable.

Solution:

$$det(\lambda I - A) = det \begin{bmatrix} \lambda & -1 & -1 \\ -1 & \lambda & -1 \\ -1 & -1 & \lambda \end{bmatrix} = det \begin{bmatrix} \lambda & -1 & -1 \\ -1 & \lambda & -1 \\ 0 & -1 - \lambda & \lambda + 1 \end{bmatrix}$$
$$= (\lambda + 1) det \begin{bmatrix} \lambda & -1 & -1 \\ -1 & \lambda & -1 \\ 0 & -1 & 1 \end{bmatrix} = (\lambda + 1) det \begin{bmatrix} \lambda & -2 & -1 \\ -1 & \lambda - 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$
$$= (\lambda + 1) (\lambda(\lambda - 1) - 2) = (\lambda + 1)(\lambda^2 - \lambda - 2)$$
$$= (\lambda + 1)^2(\lambda - 2)$$

So the **eigenvalues** of A are $\lambda_1 = -1$ and $\lambda_2 = 2$.

Eigenvectors:

$$(-I-A|O) = \begin{bmatrix} -1 & -1 & -1 & | & 0 \\ -1 & -1 & -1 & | & 0 \\ -1 & -1 & -1 & | & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 1 & | & 0 \\ 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}; \text{ take } X_1 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, X_2 = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}.$$
$$(2I-A|O) = \begin{bmatrix} 2 & -1 & -1 & | & 0 \\ -1 & 2 & -1 & | & 0 \\ -1 & -1 & 2 & | & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & -2 & | & 0 \\ 0 & 3 & -3 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1 & | & 0 \\ 0 & 1 & -1 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}; \text{ take } X_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}.$$

A is diagonalizable: because

$$P = \begin{bmatrix} X_1 \mid X_2 \mid X_3 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 1 \\ 0 & -1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

is invertible, since $det(P) = 3 \neq 0$.

- 8. [9 marks; 3 marks for each part] Indicate if the following statements are True or False, and give a brief explanation why.
 - (a) If A is a $n \times n$ matrix and $A^T = A^{-1}$, then $det(A) = \pm 1$. True False

Solution: True.

$$A^{T} = A^{-1} \implies A^{T} A = I$$

$$\implies \det(A^{T} A) = \det I$$

$$\implies \det(A^{T}) \det A = 1$$

$$\implies (\det(A))^{2} = 1$$

$$\implies \det(A) = \pm 1$$

(b) If adj(A) is the 3×3 zero matrix then so is A. True False

Solution: False. Let

$$A = \left[\begin{array}{rrrr} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{array} \right];$$

then $\operatorname{adj}(A) = O$, but $A \neq O$.

(c) If $\lambda = 0$ is an eigenvalue of A then A is invertible. **True** False

Solution: False. Let $X \neq O$ be an eigenvector of A. Then

$$AX = 0X = 0 \Rightarrow A$$
 is not invertible.

OR: if $\lambda = 0$ is an eigenvalue of A then

$$\det(0I - A) = 0 \Rightarrow \det(-A) = 0 \Rightarrow (-1)^n \det(A) = 0 \Rightarrow \det(A) = 0,$$

which means A is not invertible.

OR: give one counter example. The zero matrix is not invertible but has eigenvalue 0.