

$\odot \{ \text{vs}[K], \mathcal{L}[K] \}$

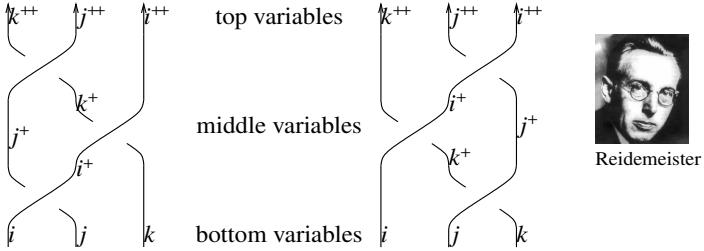
$$\begin{aligned} & \square \left\{ \{ p_1, x_1, p_2, x_2, p_3, x_3, p_4, x_4, p_5, x_5, p_6, x_6, p_7, x_7 \}, \right. \\ & \quad T \mathbb{E} \left[-2 \in -p_1 x_1 + \in p_1 x_1 + T p_2 x_1 - \in p_5 x_1 + (1-T) p_6 x_1 + \right. \\ & \quad \frac{1}{2} (-1+T) \in p_1 p_5 x_1^2 + \frac{1}{2} (1-T) \in p_5^2 x_1^2 - p_2 x_2 + p_3 x_2 - p_3 x_3 + \\ & \quad \in p_3 x_3 + T p_4 x_3 - \in p_7 x_3 + (1-T) p_8 x_3 + \frac{1}{2} (-1+T) \in p_3 p_7 x_3^2 + \\ & \quad \frac{1}{2} (1-T) \in p_7^2 x_3^2 - p_4 x_4 + \in p_4 x_4 + p_5 x_4 - p_5 x_5 + p_6 x_5 - \\ & \quad \in p_1 p_5 x_1 x_5 + \in p_5^2 x_1 x_5 - \in p_2 x_6 + (1-T) p_3 x_6 - p_6 x_6 + \\ & \quad \in p_6 x_6 + T p_7 x_6 + \in p_2^2 x_2 x_6 - \in p_2 p_6 x_2 x_6 + \frac{1}{2} (1-T) \in p_2^2 x_6^2 + \\ & \quad \left. \frac{1}{2} (-1+T) \in p_2 p_6 x_6^2 - p_7 x_7 + p_8 x_7 - \in p_3 p_7 x_3 x_7 + \in p_7^2 x_3 x_7 \right] \} \end{aligned}$$

$\odot \$\pi = \text{Normal}[\# + 0[\epsilon]^2] \& \int \mathcal{L}[K] \text{d} \text{vs}[K]$

$$\square \frac{\frac{1}{2} T \mathbb{E} \left[-\frac{(-1+T)^2 (1+T^2)}{(1-T+T^2)^2} \in \right]}{1-T+T^2}$$

A faster program to compute ρ_1 , and more stories about it, are at [BV2].

Invariance Under Reidemeister 3.



$$\begin{aligned} & \odot \text{lhs} = \int (\mathcal{L} /@ (X_{i,j}[1] X_{i+1,k}[1] X_{j+1,k+1}[1])) \\ & \quad \text{d}\{p_{i+1}, p_{j+1}, p_{k+1}, x_{i+1}, x_{j+1}, x_{k+1}\}; \\ & \text{rhs} = \int (\mathcal{L} /@ (X_{j,k}[1] X_{i,k+1}[1] X_{i+1,j+1}[1])) \\ & \quad \text{d}\{x_{i+1}, p_{i+1}, p_{j+1}, p_{k+1}, x_{j+1}, x_{k+1}\}; \\ & \text{lhs} === \text{rhs} \end{aligned}$$

$\square \text{False}$

Invariance Under Reidemeister 3, Take 2.

$$\begin{aligned} & \odot \text{lhs} = \int (\mathcal{L} /@ (X_{i,j}[1] X_{i+1,k}[1] X_{j+1,k+1}[1])) \\ & \quad \text{d}\{x_i, x_j, x_k, p_{i+1}, p_{j+1}, p_{k+1}, x_{i+1}, x_{j+1}, x_{k+1}\}; \\ & \text{rhs} = \int (\mathcal{L} /@ (X_{j,k}[1] X_{i,k+1}[1] X_{i+1,j+1}[1])) \\ & \quad \text{d}\{x_i, x_j, x_k, x_{i+1}, p_{i+1}, p_{j+1}, p_{k+1}, x_{j+1}, x_{k+1}\}; \\ & \text{lhs} === \text{rhs} \end{aligned}$$

$\square \text{True}$

$\odot \text{lhs}$

$\square \text{Degenerate } 0!$

Invariance Under Reidemeister 3, Take 3.

$$\begin{aligned} & \odot \text{lhs} = \int (\mathbb{E} [\dot{x} \pi_i p_i + \dot{x} \pi_j p_j + \dot{x} \pi_k p_k] \times \mathcal{L} /@ (X_{i,j}[1] X_{i+1,k}[1] X_{j+1,k+1}[1])) \\ & \quad \text{d}\{p_i, p_j, p_k, x_i, x_j, x_k, p_{i+1}, p_{j+1}, p_{k+1}, x_{i+1}, x_{j+1}, x_{k+1}\}; \\ & \text{rhs} = \int (\mathbb{E} [\dot{x} \pi_i p_i + \dot{x} \pi_j p_j + \dot{x} \pi_k p_k] \times \mathcal{L} /@ (X_{j,k}[1] X_{i,k+1}[1] X_{i+1,j+1}[1])) \\ & \quad \text{d}\{p_i, p_j, p_k, x_i, x_j, x_k, p_{i+1}, p_{j+1}, p_{k+1}, x_{i+1}, x_{j+1}, x_{k+1}\}; \\ & \text{lhs} == \text{rhs} \\ & \square \text{True} \\ & \odot \text{lhs} \\ & \square T^{3/2} \mathbb{E} \left[\begin{aligned} & -\frac{3\epsilon}{2} + \dot{x} T^2 p_{2+i} \pi_i - \dot{x} (-1+T) T p_{2+j} \pi_i + \dot{x} T^2 \in p_{2+j} \pi_i - \dot{x} (-1+T) p_{2+k} \pi_i + \\ & \dot{x} T \in p_{2+k} \pi_i - \frac{1}{2} (-1+T) T^3 \in p_{2+i} p_{2+j} \pi_i^2 + \frac{1}{2} (-1+T) T^3 \in p_{2+k}^2 \pi_i^2 - \\ & \frac{1}{2} (-1+T) T^2 \in p_{2+i} p_{2+k} \pi_i^2 + \frac{1}{2} (-1+T)^2 T \in p_{2+j} p_{2+k} \pi_i^2 + \\ & \frac{1}{2} (-1+T) T \in p_{2+k}^2 \pi_i^2 + \dot{x} T p_{2+j} \pi_j - \dot{x} T \in p_{2+j} \pi_j - \dot{x} (-1+T) p_{2+k} \pi_j + \\ & \dot{x} (-1+2T) \in p_{2+k} \pi_j + T^3 \in p_{2+i} p_{2+j} \pi_i \pi_j - T^3 \in p_{2+j}^2 \pi_i \pi_j - \\ & (-1+T) T^2 \in p_{2+i} p_{2+k} \pi_i \pi_j + (-1+T)^2 T \in p_{2+j} p_{2+k} \pi_i \pi_j + \\ & (-1+T) T \in p_{2+k}^2 \pi_i \pi_j - \frac{1}{2} (-1+T) T \in p_{2+j} p_{2+k} \pi_j^2 + \frac{1}{2} (-1+T) T \in p_{2+k}^2 \pi_j^2 + \\ & \dot{x} p_{2+k} \pi_k - 2 \dot{x} \in p_{2+k} p_{2+k} \pi_k + T^2 \in p_{2+i} p_{2+k} \pi_i \pi_k - (-1+T) T \in p_{2+j} p_{2+k} \pi_i \pi_k - \\ & T \in p_{2+k}^2 \pi_i \pi_k + T \in p_{2+j} p_{2+k} \pi_j \pi_k - T \in p_{2+k}^2 \pi_j \pi_k \end{aligned} \right] \end{aligned}$$

Invariance under the other Reidemeister moves is proven in a similar way. See IType.nb at [ωεβ/ap](#).

There's more! To get sl_2 invariants mod ϵ^3 , add the following to $L(X_{ij}^+)$, $L(X_{ij}^-)$, and $L(C_i^\varphi)$, respectively (and see More.nb at [ωεβ/ap](#) for the verifications):

$\odot \epsilon^2 r_2[1, i, j]$

$$\square \frac{1}{12} \epsilon^2 (-6 p_i x_i + 6 p_j x_i - 3 (-1+3T) p_i p_j x_i^2 + 3 (-1+3T) p_j^2 x_i^2 + 4 (-1+T) p_i^2 p_j x_i^3 - 2 (-1+T) (5+T) p_i p_j^2 x_i^3 + 2 (-1+T) (3+T) p_j^3 x_i^3 + 18 p_i p_j x_i x_j - 18 p_j^2 x_i x_j - 6 p_i^2 p_j x_i^2 x_j + 6 (2+T) p_i p_j^2 x_i^2 x_j - 6 (1+T) p_j^3 x_i^2 x_j - 6 p_i p_j^2 x_i x_j^2 + 6 p_j^3 x_i x_j^2)$$

$\odot \epsilon^2 r_2[-1, i, j]$

$$\square \frac{1}{12 T^2} \epsilon^2 (-6 T^2 p_i x_i + 6 T^2 p_j x_i + 3 (-3+T) T p_i p_j x_i^2 - 3 (-3+T) T p_j^2 x_i^2 - 4 (-1+T) T p_i^2 p_j x_i^3 + 2 (-1+T) (1+5T) p_i p_j^2 x_i^3 - 2 (-1+T) (1+3T) p_j^3 x_i^3 + 18 T^2 p_i p_j x_i x_j - 18 T^2 p_j^2 x_i x_j - 6 T^2 p_i^2 p_j x_i^2 x_j + 6 T (1+2T) p_i p_j^2 x_i^2 x_j - 6 T (1+T) p_j^3 x_i^2 x_j - 6 T^2 p_i p_j^2 x_i x_j^2 + 6 T^2 p_j^3 x_i x_j^2)$$

$\odot \epsilon^2 \gamma_2[\varphi, i]$

$$\square -\frac{1}{2} \epsilon^2 \varphi^2 p_i x_i$$

Even more! • The sl_2 formulas mod ϵ^4 are in the last page of the handout of [BN3].

- Using [GPV] we can show that every finite type invariant is I-Type.
- Probably, $\langle \text{Reshetikhin-Turaev} \rangle \subset \langle \text{I-Type} \rangle$ efficiently.
- Possibly, $\langle \text{Rozansky Polynomials} \rangle \subset \langle \text{I-Type} \rangle$ efficiently.
- Knot signatures are I-Type, at least mod 8.
- We already have some work on sl_3 , and it leads to the strongest genuinely-computable knot invariant presently known.