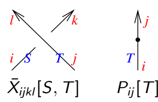
Contractions!

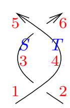
```
c_{x_,y_}[w_Wedge] := Module[{i, j},
   {i} = FirstPosition[w, x, {0}]; {j} = FirstPosition[w, y, {0}];
   { w                                            (i == 0) ∧ (j == 0)
   { (-1)^(i+j+If[i>j,0,1]) Delete[w, {{i}, {j}}]  (i > 0) ∧ (j > 0)
  ];
c_{x_,y_}[ℰ_] := ℰ /. w_Wedge :> c_{x,y}[w]
WExp[a∧b + 2 c∧d]
c_{d,c}@WExp[a∧b + 2 c∧d]
Wedge[] + a∧b + 2 c∧d + 2 a∧b∧c∧d
-Wedge[] - a∧b
```

The negative crossing and the "point":




```
𝒜[X̄_{i_,j_,k_,l_}[S_, T_]] := 𝒜[{i, j}, {k, l}, ⟨|ξ_i → S, ξ_j → T, x_k → S, x_l → T|⟩,
   Expand[T^{1/2} WExp[Expand[{ξ_i, ξ_j}.( T^-1  0 ; 1 - T^-1  1 ).{x_k, x_l}] /. ξ_a_ x_b_ :> ξ_a ∧ x_b]]];
𝒜[X̄_{i_,j_,k_,l_}] := 𝒜[X̄_{i,j,k,l}[τ_i, τ_j]];
𝒜[P_{i_,j_}[T_]] := 𝒜[{i}, {j}, ⟨|ξ_i → T, x_j → T|⟩, WExp[ξ_i ∧ x_j]];
𝒜[P_{i_,j_}] := 𝒜[P_{i,j}[τ_i]]
```

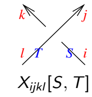
The union operation on $\mathcal{A}$'s (implemented as "multiplication"):




```
𝒜 /: 𝒜[is1_, os1_, cs1_, w1_] × 𝒜[is2_, os2_, cs2_, w2_] :=
  𝒜[is1 ⋃ is2, os1 ⋃ os2, Join[cs1, cs2], WP[w1, w2]]
Short[𝒜[X_{2,4,3,1}[S, T]] × 𝒜[X̄_{3,4,6,5}], 5]
𝒜[{1, 2, 3, 4}, {3, 4, 5, 6},
 ⟨|ξ2 → S, x4 → T, x3 → S, ξ1 → T, ξ3 → τ3, ξ4 → τ4, x6 → τ3, x5 → τ4|⟩, √τ4 Wedge[]/√T -
   √τ4 x3∧ξ1/√T + √T √τ4 x3∧ξ1 - √T √τ4 x3∧ξ2 - √τ4 x4∧ξ1/√T - √τ4 x5∧ξ4/√T -
   x6∧ξ3/(√T √τ4) + <<40>> + √T x3∧x5∧x6∧ξ1∧ξ3∧ξ4/√τ4 - √T x3∧x5∧x6∧ξ2∧ξ3∧ξ4/√τ4 -
   x4∧x5∧x6∧ξ1∧ξ3∧ξ4/(√T √τ4) + √T x3∧x4∧x5∧x6∧ξ1∧ξ2∧ξ3∧ξ4/√τ4]
```

Automatic and intelligent multiple contractions:

```
c@𝒜[is_, os_, cs_, w_] := Fold[c_{#2,#2}[#1] &, 𝒜[is, os, cs, w], is ⋂ os]
𝒜[{A_𝒜}] := c[A];
𝒜[{A1_𝒜, As__𝒜}] := Module[{A2},
  A2 = First@MaximalBy[{As}, Length[A1[[1]] ⋂ #[[2]]] + Length[A1[[2]] ⋂ #[[1]]] &];
  𝒜[Join[{c[A1 A2]}, DeleteCases[{As}, A2]]] ]
𝒜[𝒪s_List] := 𝒜[𝒜 /@ 𝒪s]
c[𝒜[X_{2,4,3,1}[S, T]] × 𝒜[X̄_{3,4,6,5}]]
𝒜[{1, 2}, {5, 6}, ⟨|ξ2 → S, ξ1 → T, x6 → S, x5 → T|⟩,
 Wedge[] - x5∧ξ1 - x6∧ξ2 - x5∧x6∧ξ1∧ξ2]
𝒜@{𝒜[X_{2,4,3,1}[S, T]], 𝒜[X̄_{3,4,6,5}]}
𝒜[{1, 2}, {5, 6}, ⟨|ξ2 → S, ξ1 → T, x6 → S, x5 → T|⟩,
 Wedge[] - x5∧ξ1 - x6∧ξ2 - x5∧x6∧ξ1∧ξ2]
```



`𝒜[is,os,cs,w]` is also a container for the values of the $\mathcal{A}$-invariant of a tangle. In it, `is` are the labels of the input strands, `os` are the labels of the output strands, `cs` is an assignment of colours (namely, variables) to all the ends $\{\xi_i\}_{i\in \mathrm{is}} \sqcup \{x_j\}_{j\in \mathrm{os}}$, and `w` is the "payload": an element of $\Lambda(\{\xi_i\}_{i\in \mathrm{is}} \sqcup \{x_j\}_{j\in \mathrm{os}})$.

```
𝒜[X_{i_,j_,k_,l_}[S_, T_]] := 𝒜[{l, i}, {j, k}, ⟨|ξ_i → S, x_j → T, x_k → S, ξ_l → T|⟩,
   Expand[T^{-1/2} WExp[Expand[{ξ_l, ξ_i}.( 1  1 - T ; 0  T ).{x_j, x_k}] /. ξ_a_ x_b_ :> ξ_a ∧ x_b]]];
𝒜[X_{1,2,3,4}[u, v]]
𝒜[{4, 1}, {2, 3}, ⟨|ξ1 → u, x2 → v, x3 → u, ξ4 → v|⟩,
 Wedge[]/√v - x2∧ξ4/√v - √v x3∧ξ1 - x3∧ξ4/√v + √v x3∧ξ4 + √v x2∧x3∧ξ1∧ξ4]
𝒜[X_{i_,j_,k_,l_}] := 𝒜[X_{i,j,k,l}[τ_i, τ_l]]
```

The linear structure on $\mathcal{A}$'s:

```
𝒜 /: α_ × 𝒜[is_, os_, cs_, w_] := 𝒜[is, os, cs, Expand[α w]]
𝒜 /: 𝒜[is1_, os1_, cs1_, w1_] + 𝒜[is2_, os2_, cs2_, w2_] /;
  (Sort@is1 == Sort@is2) ∧ (Sort@os1 == Sort@os2) ∧
   (Sort@Normal@cs1 == Sort@Normal@cs2) := 𝒜[is1, os1, cs1, w1 + w2]
```

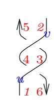
Deciding if two $\mathcal{A}$'s are equal:

```
𝒜 /: 𝒜[is1_, os1_, _, w1_] ≡ 𝒜[is2_, os2_, _, w2_] :=
 TrueQ[(Sort@is1 === Sort@is2) ∧ (Sort@os1 === Sort@os2) ∧
   PowerExpand[w1 == w2]]
```

Contractions of $\mathcal{A}$-objects:

```
c_{h_,t_}@𝒜[is_, os_, cs_, w_] := 𝒜[
   DeleteCases[is, t], DeleteCases[os, h], KeyDrop[cs, {x_h, ξ_t}], c_{x_h,ξ_t}[w]
  ] /. If[MatchQ[cs[ξ_t], τ_], cs[ξ_t] → cs[x_h], cs[x_h] → cs[ξ_t]];
c_{4,4}[𝒜[X_{2,4,3,1}[S, T]] × 𝒜[X̄_{3,4,6,5}]]
𝒜[{1, 2, 3}, {3, 5, 6}, ⟨|ξ2 → S, x3 → S, ξ1 → T, ξ3 → τ3, x6 → τ3, x5 → T|⟩,
 Wedge[] - x3∧ξ1 + T x3∧ξ1 - T x3∧ξ2 - x5∧ξ1 - x6∧ξ1 + x6∧ξ1/T - x6∧ξ3/T +
  T x3∧x5∧ξ1∧ξ2 - x3∧x6∧ξ1∧ξ2 + T x3∧x6∧ξ1∧ξ2 + x3∧x6∧ξ1∧ξ3 -
  x3∧x6∧ξ1∧ξ3/T - x3∧x6∧ξ2∧ξ3 - x5∧x6∧ξ1∧ξ3/T - x3∧x5∧x6∧ξ1∧ξ2∧ξ3]
```

4. Skein relations and evaluations for $\mathcal{A}$




```
𝒜@{X̄_{4,1,6,3}[v, u], X̄_{3,2,5,4}}
𝒜[{1, 2}, {5, 6}, ⟨|ξ2 → v, x5 → u, ξ1 → u, x6 → v|⟩,
 √u √v Wedge[] - √u x5∧ξ1/√v + √u x5∧ξ2/√v - √u √v x5∧ξ2 + √v x6∧ξ1/√u - √u √v x6∧ξ1 -
  √v x6∧ξ2/√u - √u x5∧x6∧ξ1∧ξ2/√v - √v x5∧x6∧ξ1∧ξ2/√u + √u √v x5∧x6∧ξ1∧ξ2]
```

Video and more at `http://www.math.toronto.edu/~drorbn/Talks/MoscowByWeb-2104/`