

$\mathbb{E} \left[ a_3 \alpha_1 + a_3 \alpha_2 + t_3 (\tau_1 + \tau_2), \right.$ $y_3 \eta_1 + e^{-\gamma \alpha_1} y_3 \eta_2 + e^{-\gamma \alpha_2} x_3 \xi_1 + \frac{(1 - T_3) \eta_2 \xi_1}{\hbar} + x_3 \xi_2,$ $1 + \frac{1}{4 \hbar} \eta_2 \xi_1 (8 \hbar a_3 T_3 + 4 e^{-\gamma \alpha_1 - \gamma \alpha_2} \gamma \hbar^2 x_3 y_3 + 2 e^{-\gamma \alpha_1} \gamma \hbar y_3 \eta_2 -$ $6 e^{-\gamma \alpha_1} \gamma \hbar T_3 y_3 \eta_2 + 2 e^{-\gamma \alpha_2} \gamma \hbar x_3 \xi_1 - 6 e^{-\gamma \alpha_2} \gamma \hbar T_3 x_3 \xi_1 +$ $\gamma \eta_2 \xi_1 - 4 \gamma T_3 \eta_2 \xi_1 + 3 \gamma T_3^2 \eta_2 \xi_1) \in O[\epsilon]^2 \right]$	$R[QU, kk] :=$ $R[QU, kk] = \mathbb{E} \left[ -\frac{\hbar a_2 t_1}{\gamma}, \hbar x_2 y_1, \right.$ $\text{Series} \left[ e^{\hbar \gamma^{-1} t_1 a_2 - \hbar y_1 x_2} \right.$ $\left. \left( e^{\hbar b_1 a_2} e_{q_k, kk} [\hbar y_1 x_2] / . b_1 \rightarrow \gamma^{-1} (e a_1 - t_1) \right), \right.$ $\left. \{e, \theta, kk\} \right];$
$S[U_, kk_] := S[U, kk] = \text{Module}[\{OE\},$ $OE = m_{3,2,1 \rightarrow 1}[\text{Exp}_{QU_1, sk}[\eta, S_1[QU[y_1]] /. QU \rightarrow \text{Times}],$ $\text{Exp}_{QU_2, sk}[\alpha, S_2[QU[a_2]] /. QU \rightarrow \text{Times}],$ $\text{Exp}_{QU_3, sk}[\xi, S_3[QU[x_3]] /. QU \rightarrow \text{Times}]];$ $\mathbb{E}[-t_1 \tau_1 + OE[[1]], OE[[2]], OE[[3]]] / .$ $\{\eta \rightarrow \eta_1, \alpha \rightarrow \alpha_1, \xi \rightarrow \xi_1\};$	$tR_{i_, j_} :=$ $R[\$U, \$k] / . \{(v : t   T   y   a   x)_1 \rightarrow v_i, (v : t   T   y   a   x)_2 \rightarrow v_j\};$ $\overline{tR}_{i_, j_} := \overline{tR}_{i,j} = tR_{i,j} \sim B_j \sim tS_j;$
$tS_i := S[\$U, \$k] / . \{(v : \tau   \eta   \alpha   \xi)_1 \rightarrow v_i, (v : t   T   y   a   x)_1 \rightarrow v_i\};$	$\{tR_{1,2}, \overline{tR}_{1,2}\}$ $\left\{ \mathbb{E} \left[ -\frac{\hbar a_2 t_1}{\gamma}, \hbar x_2 y_1, 1 + \left( \frac{\hbar a_1 a_2}{\gamma} - \frac{1}{4} \gamma \hbar^3 x_2^2 y_1^2 \right) \in + O[\epsilon]^2 \right], \right.$ $\mathbb{E} \left[ \frac{\hbar a_2 t_1}{\gamma}, -\frac{\hbar x_2 y_1}{T_1}, 1 + \frac{1}{4 \gamma T_1^2} (-4 \hbar a_1 a_2 T_1^2 - 4 \gamma \hbar^2 a_1 T_1 x_2 y_1 - 4 \gamma \hbar^2 a_2 T_1 x_2 y_1 - 3 \gamma^2 \hbar^3 x_2^2 y_1^2) \in + O[\epsilon]^2 \right]$
$tS_1$ $\mathbb{E}[-a_1 \alpha_1 - t_1 \tau_1,$ $-\epsilon^{\gamma \alpha_1} \hbar y_1 \eta_1 - \epsilon^{\gamma \alpha_1} \hbar T_1 x_1 \xi_1 + \epsilon^{\gamma \alpha_1} \eta_1 \xi_1 - \epsilon^{\gamma \alpha_1} T_1 \eta_1 \xi_1, 1 +$ $\frac{1}{\hbar T_1^2} (4 \epsilon^{\gamma \alpha_1} \gamma \hbar^2 T_1 y_1 \eta_1 - 4 \epsilon^{\gamma \alpha_1} \hbar^2 a_1 T_1 y_1 \eta_1 - 2 \epsilon^{2 \gamma \alpha_1} \gamma \hbar^2 y_1^2 \eta_1^2 -$ $4 \epsilon^{\gamma \alpha_1} \hbar^2 a_1 T_1^2 x_1 \xi_1 - 4 \epsilon^{\gamma \alpha_1} \gamma \hbar T_1 \eta_1 \xi_1 + 8 \epsilon^{\gamma \alpha_1} \hbar a_1 T_1 \eta_1 \xi_1 +$ $4 \epsilon^{\gamma \alpha_1} \gamma \hbar T_1^2 \eta_1 \xi_1 - 4 \epsilon^{2 \gamma \alpha_1} \gamma \hbar^2 T_1 x_1 y_1 \eta_1 \xi_1 + 6 \epsilon^{2 \gamma \alpha_1} \gamma$ $\hbar y_1 \eta_1^2 \xi_1 - 2 \epsilon^{2 \gamma \alpha_1} \gamma \hbar T_1 y_1 \eta_1^2 \xi_1 - 2 \epsilon^{2 \gamma \alpha_1} \gamma \hbar^2 T_1^2 x_1^2 \xi_1^2 +$ $6 \epsilon^{2 \gamma \alpha_1} \gamma \hbar T_1 x_1 \eta_1 \xi_1^2 - 2 \epsilon^{2 \gamma \alpha_1} \gamma \hbar^2 T_1^2 x_1 \eta_1 \xi_1^2 - 3 \epsilon^{2 \gamma \alpha_1} \gamma \hbar^2 \xi_1^2 +$ $4 \epsilon^{2 \gamma \alpha_1} \gamma T_1 \eta_1^2 \xi_1^2 - \epsilon^{2 \gamma \alpha_1} \gamma T_1^2 \eta_1^2 \xi_1^2) \in O[\epsilon]^2]$	$tC \text{ is the counterclockwise spinner; } \overline{tC} \text{ is its inverse.}$ $tC_i := \mathbb{E}[\theta, \theta, T_i^{1/2} e^{-\epsilon a_i \hbar} + \theta \$k];$ $\overline{tC}_i := \mathbb{E}[\theta, \theta, T_i^{-1/2} e^{\epsilon a_i \hbar} + \theta \$k];$
$\Delta[U_, kk_] := \Delta[U, kk] = \text{Module}[\{OE\},$ $OE = \text{Block}[\{\$k = kk, \$p = kk + 1\},$ $m_{1,3,5 \rightarrow 1} @$ $m_{2,4,6 \rightarrow 2} @ \text{Times} [(* \text{ Warning:} \\ \text{ wrong unless } \$p \geq \$k+1 *)]$ $\text{ReplacePart}[1 \rightarrow 0] @$ $\text{Exp}_{QU_1, sk}[\eta, \Delta_{1 \rightarrow 1, 2}[\text{QU}[y_1]] /. QU \rightarrow \text{Times}],$ $\text{ReplacePart}[2 \rightarrow 0] @$ $\text{Exp}_{QU_3, sk}[\alpha, \Delta_{3 \rightarrow 3, 4}[\text{QU}[a_3]] /. QU \rightarrow \text{Times}],$ $\text{ReplacePart}[1 \rightarrow 0] @$ $\text{Exp}_{QU_5, sk}[\xi, \Delta_{5 \rightarrow 5, 6}[\text{QU}[x_5]] /. QU \rightarrow \text{Times}]$ $ \mathbb{E}[\tau_1 (t_1 + t_2) + \alpha_1 (a_1 + a_2), OE[[2]], OE[[3]]]; $	$\text{Block}[\{\$k = 3\}, \{tC_1, \overline{tC}_2\}]$ $\{\mathbb{E}[\theta, \theta,$ $\sqrt{T_1} - \hbar a_1 \sqrt{T_1} \in + \frac{1}{2} \hbar^2 a_1^2 \sqrt{T_1} \in^2 - \frac{1}{6} (\hbar^3 a_1^3 \sqrt{T_1}) \in^3 + O[\epsilon]^4\},$ $\mathbb{E}[\theta, \theta, \frac{1}{\sqrt{T_2}} + \frac{\hbar a_2 \epsilon}{\sqrt{T_2}} + \frac{\hbar^2 a_2^2 \epsilon^2}{2 \sqrt{T_2}} + \frac{\hbar^3 a_2^3 \epsilon^3}{6 \sqrt{T_2}} + O[\epsilon]^4]$
$t\Delta_{i \rightarrow j, k} :=$ $\Delta[\$U, \$k] / . \{(v : t   \eta   \alpha   \xi)_1 \rightarrow v_i, (v : t   T   y   a   x)_1 \rightarrow v_j, (v : t   T   y   a   x)_2 \rightarrow v_k\};$	$\text{Kink}[QU, kk] :=$ $\text{Kink}[QU, kk] =$ $\text{Block}[\{\$k = kk\}, (\overline{tR}_{1,3} \overline{tC}_2) \sim B_{1,2} \sim \overline{tm}_{1,2 \rightarrow 1} \sim B_{1,3} \sim \overline{tm}_{1,3 \rightarrow 1}];$ $tKink_i := \text{Kink}[\$U, \$k] / . \{(v : t   \eta   \alpha   \xi)_1 \rightarrow v_i\};$ $\overline{Kink}[QU, kk] :=$ $\overline{Kink}[QU, kk] =$ $\text{Block}[\{\$k = kk\}, (\overline{tR}_{1,3} tC_2) \sim B_{1,2} \sim \overline{tm}_{1,2 \rightarrow 1} \sim B_{1,3} \sim \overline{tm}_{1,3 \rightarrow 1}];$ $\overline{tKink}_i := \overline{Kink}[\$U, \$k] / . \{(v : t   \eta   \alpha   \xi)_1 \rightarrow v_i\}$
<b>Alternative Algorithms</b>	
$\lambda_{alt, k_1}[CU] := \text{If}[k == 0, 1, \text{Module}[\{eq, d, b, c, so\},$ $eq = p @ e^{\xi x cu}. p @ e^{\eta y cu} == p @ e^d y cu. p @ e^c (t_1 cu - 2 \epsilon a cu). p @ e^b x cu;$ $\{so\} = \text{Solve}[\text{Thread}[\text{Flatten} / . eq], \{d, b, c\}] / .$ $C @ 1 \rightarrow 0;$ $\text{Series}[e^{-\eta y - \xi x + \eta \xi t + c t + d y - 2 \epsilon c a + b x} / . so, \{\epsilon, \theta, k\}]];$	
<b>The Trefoil</b>	
$\text{Block}[\{\$k = 1\},$ $Z = tR_{1,5} tR_{6,2} tR_{3,7} \overline{tC}_4 \overline{tKink}_8 \overline{tKink}_9 \overline{tKink}_{10};$ $\text{Do}[Z = Z \sim B_{1,k \sim \overline{tm}_{1,k \rightarrow 1}}, \{k, 2, 10\}]; Z]$	$\mathbb{E}[\theta, \theta, \frac{T_1}{1 - T_1 + T_1^2} +$ $\left( (-2 \hbar a_1 T_1 - \gamma \hbar T_1^2 + 2 \hbar a_1 T_1^2 + 2 \gamma \hbar T_1^3 - 3 \gamma \hbar T_1^4 - 2 \hbar a_1 T_1^4 + \right.$ $2 \gamma \hbar T_1^5 + 2 \hbar a_1 T_1^5 - 2 \gamma \hbar^2 T_1 x_1 y_1 - 2 \gamma \hbar^2 T_1^4 x_1 y_1) \in /$ $(1 - 3 T_1 + 6 T_1^2 - 7 T_1^3 + 6 T_1^4 - 3 T_1^5 + T_1^6) + O[\epsilon]^2]$

diagram	$n'_k$	Alexander's $\omega^+$ Today's / Rozansky's $\rho_1^+$	genus / ribbon	diagram	$n'_k$	Alexander's $\omega^+$ Today's / Rozansky's $\rho_1^+$	genus / ribbon
	$0^a_1$	1	$0 / \checkmark$		$3^a_1$	$t - 1$	$1 / \times$
	$0$		$0 / \checkmark$		$t$		$1 / \times$
	$4^a_1$	$3 - t$	$1 / \times$		$5^a_1$	$t^2 - t + 1$	$2 / \times$
	$0$		$1 / \checkmark$		$2t^3 + 3t$		$2 / \times$
	$5^a_2$	$2t - 3$	$1 / \times$		$6^a_1$	$5 - 2t$	$1 / \checkmark$
	$5t - 4$		$1 / \times$		$t - 4$		$1 / \times$