

The sl_2 Example. Let $g^\epsilon = \langle h, e, l, f \rangle / ([h, \cdot] = 0, [e, l] = -e, [f, l] = f, [e, f] = h - 2\epsilon l)$ and let $g_k = g^\epsilon / (\epsilon^{k+1} = 0)$.

The Main g_k Theorem. The g_k -invariant of any S -component tangle T can be written in the form

$$Z(T) = \mathbb{O}\left(\omega e^{L+Q+P} : \bigotimes_{i \in S} e_i l_i f_i\right),$$

where ω is a scalar (meaning, a rational function in the variables h_i and their exponentials $t_i := e^{h_i}$), where $L = \sum a_{ij} h_i l_j$ is a balanced quadratic in the variables h_i and l_j with integer coefficients, where $Q = \sum b_{ij} e_i f_j$ is a balanced quadratic in the variables e_i and f_j with scalar coefficients b_{ij} , and where P is a polynomial in $\{\epsilon, e_i, l_i, f_i\}$ (with scalar coefficients) whose ϵ^d -term is of degree at most $2d + 2$ in $\{e_i, \sqrt{l_i}, f_i\}$. Furthermore, after setting $h_i = h$ and $t_i = t$ for all i , the invariant $Z(T)$ is poly-time computable.

The Main g_k Lemma. The following “re-ordering relations” hold:

$$\mathbb{O}(e^{\gamma l + \beta e} : le) = \mathbb{O}(e^{\gamma l + e^\gamma \beta e} : el) \quad (\text{and similarly for } fl \rightarrow lf),$$

$\mathbb{O}(e^{\beta e + \alpha f + \delta ef} : fe) = \mathbb{O}(v \oplus v(-\alpha \beta h + \beta e + \alpha f + \delta ef) + \lambda_k(\epsilon, e, l, f, \alpha, \beta, \delta) : elf)$, with $v = (1 + h\delta)^{-1}$ and where $\lambda_k(\epsilon, e, l, f, \alpha, \beta, \delta)$ is some fixed polynomial of degree at most $2k + 2$ in $\epsilon, e, \sqrt{l}, f, \alpha, \beta, \delta$, with scalar coefficients.

Demo Programs.

[ωεβ/Demo](#)

```
CF[ε_] := Module[{vars = Union@Cases[ε, e_|l_|f_, ∞]},  
 If[vars === {}, Factor[ε],  
 Total[CoefficientRules[ε, vars]] /.  
 (p_ → c_) → Factor[c] Times @@ (vars^p)]]];  
 CF[Z_E] := CF @/ ε;
```

[Formatting](#)

```
IE[i_, j_, s_] := IE[1, (-1)^s l_j, (-t)^s e_i f_j,  
 t^s e_i l_{(1+s)i-sj} f_j + (-1)^s l_i l_j + (-t^2)^s e_i^2 f_j^2 / 4];  
 IE[i_, s_] := IE[1, 0, 0, s l_i];  
 IE/: IE[1, L1_, Q1_, P1_] IE[1, L2_, Q2_, P2_] :=  
 IE[1, L1 + L2, Q1 + Q2, P1 + P2];  
 z1 = (IE[1, 11, 0] IE[4, 2, -1] IE[15, 5, 0] × Preparing the Trefoil  
 IE[6, 8, -1] IE[9, 16, 0] IE[12, 14, -1] ×  
 IE[3, -1] IE[7, +1] IE[10, -1] IE[13, +1])
```

$$\begin{aligned} & \mathbb{E}[1, -l_2 + l_5 - l_8 + l_{11} - l_{14} + l_{16}, \\ & -\frac{e_4 f_2}{t} + e_{15} f_5 - \frac{e_6 f_8}{t} + e_1 f_{11} - \frac{e_{12} f_{14}}{t} + e_9 f_{16}, \\ & -\frac{e_2^2 f_2^2}{4 t^2} + \frac{1}{4} e_{15}^2 f_5^2 - \frac{e_6^2 f_8^2}{4 t^2} + \frac{1}{4} e_1^2 f_{11}^2 - \frac{e_{12}^2 f_{14}^2}{4 t^2} + \frac{1}{4} e_9^2 f_{16}^2 + e_1 f_{11} l_1 + \\ & \frac{e_4 f_2 l_2}{t} - l_3 - l_2 l_4 + l_7 + \frac{e_6 f_8 l_8}{t} - l_6 l_8 + e_9 f_{16} l_9 - l_{10} + \\ & l_1 l_{11} + l_{13} + \frac{e_{12} f_{14} l_{14}}{t} - l_{12} l_{14} + e_{15} f_5 l_{15} + l_5 l_{15} + l_9 l_{16}] \end{aligned}$$

```
DPx→Dα,y→Dβ[P_][f_] := Differential Polynomials  
Total[CoefficientRules[P, {x, y}]] /. (Implementing P(∂α, ∂β)(f))  
({m_, n_} → c_) → c D[f, {α, m}, {β, n}]
```

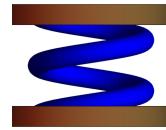
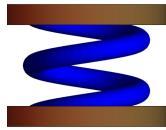


diagram	n_k^t	Alexander's ω^+ Today's / Rozansky's ρ_1^+	genus / ribbon	diagram	n_k^t	Alexander's ω^+ Today's / Rozansky's ρ_1^+	genus / ribbon
	0_1^a 0	1 0	$0 / \checkmark$ $0 / \checkmark$		3_1^a t	$t - 1$ t	$1 / \times$ $1 / \times$
	4_1^a 0	$3 - t$ 0	$1 / \times$ $1 / \checkmark$		5_1^a $2t^3 + 3t$	$t^2 - t + 1$ $2t^3 + 3t$	$2 / \times$ $2 / \times$

Video and more at <http://www.math.toronto.edu/~drorbn/Talks/Toulouse-1705/>