

MAT1344 22/1/2021

* office hr after class.

* if you're taking this for credit
please email me:

① between 1 sentence & 1 paragraph:
what was unclear?
on what should I expand?
request?

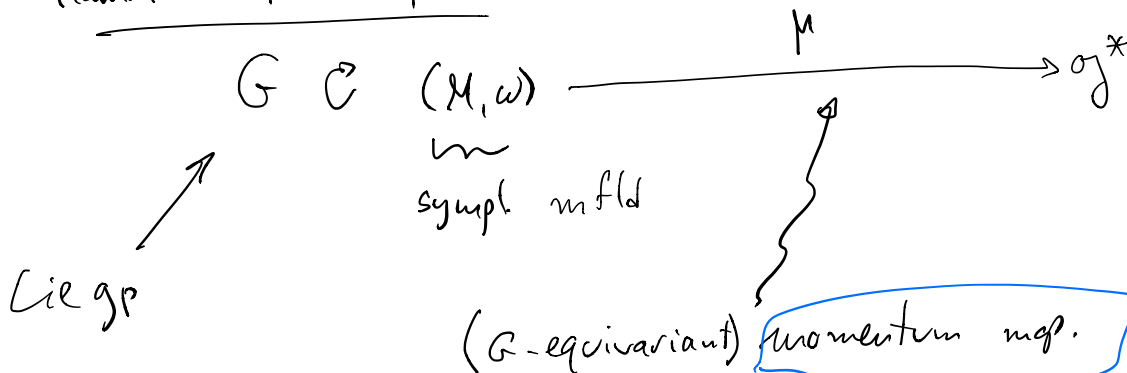
② between 1 paragraph & 1 page: MATH!
work out details of something?
from these 2 weeks.

an excellent reference on Lie groups & their actions:

John Lee "Intro to smooth manifolds"

chapters ~~7, 8, 9~~, 20, 21.

Hamiltonian G-space :



$$\mathfrak{g} = \text{Lie}(G) := T_1 G$$

$$\left\{ \frac{1}{\text{mathfrak{g}}} \right\}$$

Hamilton's equation $\forall \xi \in \mathfrak{g}$

for $\mu^\xi := \langle \mu, \xi \rangle : M \longrightarrow \mathbb{R}$

$$d\mu^\xi = -\sum_M \lrcorner \omega$$

Example. $G = (S^1)^n \hookrightarrow \mathbb{C}^n = \mathbb{R}^{2n}$

$$\omega = \sum_{j=1}^n dx_j \wedge dy_j = \sum_{j=1}^n r_j dr_j \wedge d\theta_j$$

$$(a_1, \dots, a_n) \cdot (z_1, \dots, z_n) := (a_1 z_1, \dots, a_n z_n)$$

$$\mathbb{R}^n \cong \text{Lie}(S^1)^n \xrightarrow{\xi \mapsto \xi_M} \mathcal{X}(\mathbb{C}^n)$$

vector fields

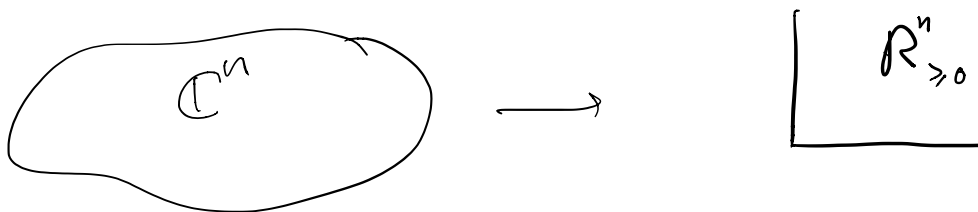
$$e_j \longmapsto \frac{\partial}{\partial \theta_j} = x_j \frac{\partial}{\partial y_j} - y_j \frac{\partial}{\partial x_j}$$

$$\mu : \mathbb{C}^n \longrightarrow (\text{Lie}(S^1)^n)^* \cong \mathbb{R}^n$$

$$\mu = (\mu_1, \dots, \mu_n)$$

$$d\mu_j = -\frac{\partial}{\partial \theta_j} \omega = r_j dr_j$$

$$\therefore \mu(z_1, \dots, z_n) = \left(\frac{|z_1|^2}{2}, \dots, \frac{|z_n|^2}{2} \right) + \text{constant}$$



Lie algebras

a Lie algebra is a vector space V
equipped with an antisymmetric bilinear map

$$[,] : V \times V \longrightarrow V$$

that satisfies Jacobi's identity:

$$\forall u, v, w \quad [u, [v, w]] + [v, [w, u]] + [w, [u, v]] = 0$$

Example $V = \mathbb{R}^{n \times n} = n \times n$ matrices
 $[A, B] = AB - BA$ for $A, B \in \mathbb{R}^{n \times n}$

Example $\mathfrak{X}(M) := \{ \text{vector fields on } M \}$

is a Lie algebra with

$$[X, Y]f = XYf - YXf \quad \forall f \in C^\infty(M)$$

Let G be a Lie group. $a, b \in G$.

$$L_a: G \rightarrow G \quad g \mapsto ag$$

$$R_b: G \rightarrow G \quad g \mapsto gb$$

$$(L_a)_*: TG \longrightarrow TG$$

write as $\xi \mapsto a\xi$

Here $\xi \in T_g G$ is represented by $\gamma: \mathbb{R} \rightarrow G$
 $\gamma(0) = g$

and $a\xi \in T_{ag} G$ is represented by $t \mapsto a\gamma(t)$

A vector field X on G is left invariant if

$$\forall a, g \in G \quad a \cdot (X|_g) = X|_{a \cdot g}$$

This holds $\Leftrightarrow \forall f \in C^\infty(G)$

$$(Xf)(ag) = X(g \mapsto f(ag))$$

$\therefore$ If X, Y are left invariant v. fields,

$$\text{so is } [X, Y].$$

(this generalizes to vector fields
on any mfd w/ G -action)

$$\mathfrak{g} := T_1 G \quad \longleftrightarrow \quad \left\{ \begin{array}{l} \text{left invariant} \\ \text{vector fields on } G \end{array} \right\}$$

$$\xi \quad \longleftrightarrow \quad X \quad \text{s.t.} \quad X|_g = g \cdot \xi$$

Define $[\cdot, \cdot]$ on $\mathfrak{g}$ through this bijection!

Lemma
For every homomorphism of Lie groups

$$\psi : H \longrightarrow G,$$

$$\begin{array}{ccc} d\psi|_1 : T_1 H & \longrightarrow & T_1 G \\ \downarrow & \parallel & \downarrow \\ \mathfrak{t} & \text{Lie}(H) & \text{Lie}(G) \\ & \parallel & \parallel \\ & \mathfrak{h} & \mathfrak{g} \end{array}$$

is a homomorphism of Lie algebras.

Isotropy representation

Let $G \curvearrowright N$

Let $x \in N$ be a fixed point, i.e.

$$\forall g \in G \quad g \cdot x = x$$

i.e. $G \cdot x = \{x\}$

i.e. $\text{Stab}(x) = G$

Then $\forall a \in G \quad a: N \longrightarrow N$
 $x \longmapsto x$

induces $a_x: T_x N \longrightarrow T_x N$

$$\parallel \frac{da}{dx}$$

$a \mapsto a_x$ is a linear representation

$$G \curvearrowright T_x N.$$

$\equiv$: "the isotropy representation".

Note:

if $G \curvearrowright (M, \omega)$ preserves ω

i.e. $\forall a \in G \quad a^* \omega = \omega$

Then $G \curvearrowright T_x M$ preserves $\omega|_x$.

Coadjoint action

$$G \curvearrowright \mathfrak{g}^*$$

start with $G \curvearrowright G = M$ by conjugation:

$$a: \mathfrak{g} \longmapsto a \mathfrak{g} a^{-1}$$

It preserves 1.

Its linearization: $\text{Ad}: G \curvearrowright T_1 G = \mathfrak{g}$

is called the adjoint representation

The dual representation
is called the coadjoint representation.

$$\text{Ad}^*: G \curvearrowright \mathfrak{g}^*$$

$$\forall a \in G \quad \begin{aligned} \text{Ad}(a) &: \mathfrak{g} \rightarrow \mathfrak{g} \\ \text{Ad}^*(a) &: \mathfrak{g}^* \rightarrow \mathfrak{g}^* \end{aligned}$$

$$\langle \text{Ad}^*(a) \psi, \xi \rangle = \langle \psi, \text{Ad}(a^{-1})(\xi) \rangle \quad \begin{aligned} &\forall \xi \in \mathfrak{g} \\ &\forall \psi \in \mathfrak{g}^* \end{aligned}$$

We require a momentum map

$$\mu: M \longrightarrow \mathfrak{g}^*$$

to be equivariant wrt the given G action on M
& the coadjoint action on $\mathfrak{g}^*$.

Definition.

The coadjoint orbits of G
are the orbits of $\text{Ad}^*: G \curvearrowright \mathfrak{g}^*$.

Let $M \subset \mathfrak{g}^*$ be a coadjoint orbit of G .

- M is a manifold.

M is a weakly embedded subnd of $\mathfrak{g}^*$
($\Rightarrow \exists!$ ind str on M st. $M \hookrightarrow \mathfrak{g}^*$
is an immersion)

- M is a sympl. mfd.

we equip M with the
"Kirillov-Kostant-Souriau sympl. form"

- $G \curvearrowright M$ transitively

- The inclusion map $\mu: M \hookrightarrow \mathfrak{g}^*$
is a momentum map.

Office hour:

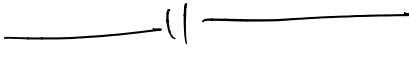
$$\psi : M \longrightarrow N$$

smooth map of manifolds.

$$x \in M$$

$$y = \psi(x) \in N$$

$T_x M$ = "linear approximation of M at x "

$T_y N$ = "  N at y "

$$\psi_* = d\psi|_x : T_x M \longrightarrow T_y N$$

= "linear approximation of ψ at x ".

In coordinates:

$$\text{if } \psi : (u_1, \dots, u_m) \longmapsto (v_1, \dots, v_n)$$

$$v_j = \psi_j(u_1, \dots, u_m)$$

$$x=0$$

$$\psi(0) = 0$$

$$y=0$$

$$\text{Then } L := \psi_* : \mathbb{R}^m \longrightarrow \mathbb{R}^n$$

is repr. by the matrix $\left[\frac{\partial \psi_j}{\partial u_i} \right]$.

$$\left(\begin{array}{l} \psi(u) = \psi(0) + L(u) + \text{Error}(u) \\ \text{and } \frac{\|\text{Error}(u)\|}{\|u\|} \xrightarrow{u \rightarrow 0} 0 \end{array} \right)$$

Let G be a ^{connected} compact Lie gp.
 $G \subseteq G_{\mathbb{C}}$ its complexification
 (the connected $\mathbb{C}P$ Lie gp
 st. $\mathfrak{g}_{\mathbb{C}} = \mathfrak{g} \otimes \mathbb{C}$)

$$\begin{array}{ccc} B \subset G_{\mathbb{C}} & \xrightarrow{\text{Borel subgp.}} & \\ \cup & & \cup \\ T \subset G & & \end{array}$$

↳ maximal torus

Take $M := \text{Ad}^*(G) \cdot \lambda$ $\lambda \in \mathfrak{g}^*$ st.
 $\text{stabil}(\lambda) = T$

$$\begin{array}{ccc} G & \longrightarrow & M \\ a & \longmapsto & \text{Ad}^*(a)(\lambda) \end{array}$$

induces $G/T \xrightarrow{\cong} M$ symp.

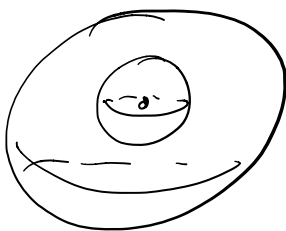
$$\begin{array}{ccc} G & \hookrightarrow & G_{\mathbb{C}} \\ \downarrow & & \downarrow \\ M \cong G/T & \xrightarrow{\cong} & G_{\mathbb{C}}/B \end{array}$$

complex
mfld

$$Ad^*: SU(2) \hookrightarrow \mathbb{R}^3$$

$$\text{through } SU(2) \longrightarrow SO(3)$$

orbits:



Kirillov-Kostant-Souriau:

$$\omega = \frac{x dy - y dx + z dx + x dz - y dz - z dy}{x^2 + y^2 + z^2}$$

on each sphere

need to check.

$$M = G/T$$

Tangent :

$$\mathfrak{g}/\mathfrak{t}$$

$$T \hookrightarrow \mathfrak{g}$$

f. pt set $\mathfrak{t}$

$$T \hookrightarrow \mathfrak{g}/\mathfrak{t}$$

with trivial fixed subspace.

Construct coadjoint orbits
as Kähler reduction?
(of T^*G ?)

G
Compact

$G \curvearrowright M$

$$G \cdot x = \{x\}$$

Then $\exists$ G -invariant $U \ni x$ in M

and

a G -invariant $\Omega \ni 0$ in $T_x M$
with the isotr. repr.

and

a G -equivariant diffeo

$$\begin{array}{ccc} U & \xrightarrow{\quad} & \Omega \\ x & \xrightarrow{\quad} & 0 \end{array}$$

can take this
to be all of
 $T_x M$

Momentum map $\mu: M \longrightarrow \mathfrak{g}^*$

$$\begin{array}{ccc} M \times \mathfrak{g} & \longrightarrow & \mathbb{R} \\ m, \xi & \longmapsto & \mu^\xi(m) \end{array}$$

$$\mu^\# : \begin{array}{ccc} \mathfrak{g} & \longrightarrow & C^\infty(M) \\ \xi & \longmapsto & (m \mapsto \mu^\xi(m)) \end{array}$$

If G is connected & μ satisfies Hamilton's equation:

μ is G -equivariant

$\Leftrightarrow \mu^\#$ is a Lie algebra morphism

$$(\mathfrak{g}, [\cdot, \cdot]) \longmapsto (C^\infty(M), \{\cdot, \cdot\})$$

↗
Poisson bracket