

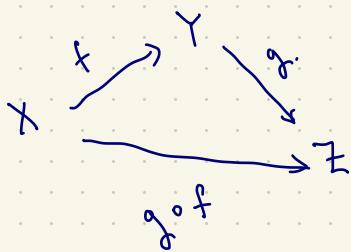
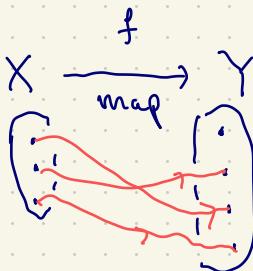
Finite Sets

X

construct

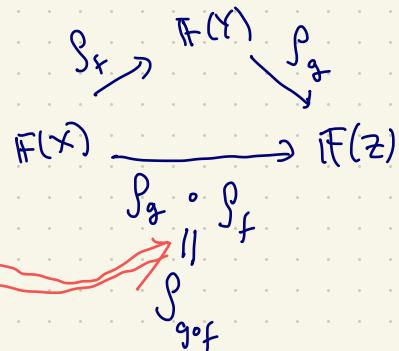
Finite-dim v.spaces. / \mathbb{F}

$\mathbb{F}(X) =$ formal linear combos of elts of X .



construct

$\rho_f: \mathbb{F}(X) \rightarrow \mathbb{F}(Y)$.
Linear map.



"compos. of linear maps of f, g
is the linear map of compos. of
 f, g "

Functor

from

Sets

to

Vector Spaces

↙ categories ↗

Review: V, W fd.
v.s.p./F $\Rightarrow L(V, W) \rightarrow A$ can be described as
a $\dim W \times \dim V$ matrix of elts in F: choose bases
 β for V , γ for W and write

$$M(A, \beta, \gamma) = \gamma [A]_{\beta} = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & & \vdots \\ a_{k1} & \cdots & a_{kn} \end{bmatrix}$$

(dim $W=k$, dim $V=n$)

Changing β , γ will affect the matrix $k \times k$ $k \times n$ $n \times n$
to $\beta', \gamma' \Rightarrow$

$$\gamma' [A]_{\beta'} = \underbrace{\gamma' [I_w]}_{k \times k \text{ invertible matrix}} \gamma [A]_{\beta} \underbrace{\gamma' [I_v]}_{n \times n \text{ invertible matrix}} \beta' \quad Q = \beta' [I]_{\beta}$$

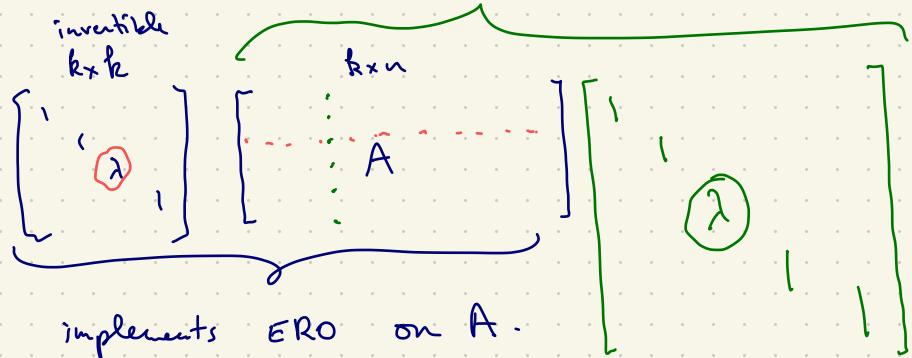
$$P \qquad \qquad \qquad Q^{-1}$$

To emphasize the fact that the initial and final $k \times n$ matrices represent the same linear map, we can define

two matrices A, A' to be "equivalent" when $\exists P, Q$ invertible matrices s.t.

$$A' = P A Q^{-1}$$

el.
implements column operations.



Simplify given $k \times n$ matrix A without changing its equivalence class.

① GE (Row ops) to RRE

$$\left[\begin{array}{cccc|cc} 1 & * & 0 & 0 & * & 0 & * \\ & & 0 & * & * & 0 & * \\ & & 0 & * & * & 0 & * \\ & & 1 & * & * & 0 & * \\ & & 0 & * & * & 0 & * \\ \hline 0 & & & & & & \end{array} \right]$$

② GE (Col. ops) to clear all unknowns (*)

result

$$\left[\begin{array}{cccc|cc} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ & 1 & 0 & 0 & 0 & 0 & 0 \\ & 0 & 1 & 0 & 0 & 0 & 0 \\ & 0 & 0 & 1 & 0 & 0 & 0 \\ & 0 & 0 & 0 & 1 & 0 & 0 \\ & 0 & 0 & 0 & 0 & 1 & 0 \\ \hline 0 & & & & & & \end{array} \right]$$

③ Column switching to bring everything to right.

$$\left[\begin{array}{cccc|cc} 1 & 1 & 0 & & & & \\ 1 & 1 & 1 & 0 & & & \\ 1 & 1 & 1 & 1 & 0 & & \\ 1 & 1 & 1 & 1 & 1 & 0 & \\ \hline 0 & & & & & & \end{array} \right]$$

offset diagonal

Thm:

Every $k \times n$ matrix A is equiv. to

block matrix

$$\left[\begin{array}{c|cc} \bullet & & \\ \hline 0 & I & \\ & 0 & \end{array} \right] \quad \begin{array}{l} r \times r \\ r = \text{rk } A \end{array}$$

In terms of bases : for any linear

$$\text{map } A : V \rightarrow W$$

exists bases β γ s.t.

$$(e_1, \dots, e_n) \quad (f_1, \dots, f_k).$$

$$A(e_1) = f_1$$

$$A(e_2) = f_2$$

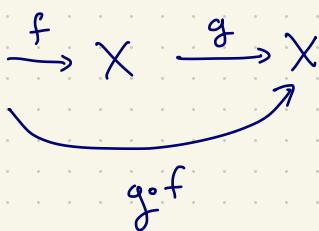
:

$$A(e_r) = f_r$$

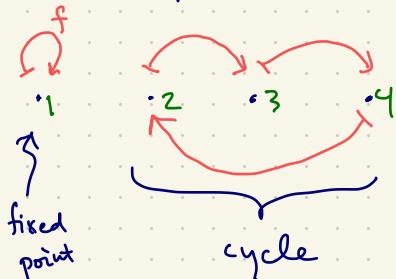
$$A(e_i) = 0 \quad \forall i > r$$

$$\gamma [A]_{\beta} = \left[\begin{array}{c|c} I_{r \times r} & 0 \\ \hline 0 & 0 \end{array} \right]$$

Recall studied maps $X \xrightarrow{f} X \xrightarrow{g} X$



self-maps of a set.



represent the map f . in cycle notation

(2 3 4)

There is a corresponding description for Linear Operators

"Linear operators on V " = $L(V, V)$.

key difference: since domain + codomain coincide,
we need not choose two bases;
one basis for V suffices.

i.e. $A \in L(V, V)$ has a matrix after single choice $\beta = (e_1, \dots, e_n)$ basis for V .

$$[\beta]_{\beta}^{\beta} [A]_{\beta} = \left[\begin{array}{c} \\ \\ \\ \text{nxn} \\ \text{(square)} \\ \text{matrix} \end{array} \right]$$

⇒ have a different equivalence relation on nxn matrices

Def: Two $n \times n$ matrices A, A' are Similar or Conjugate when $\exists P$ invertible $n \times n$ st.

$$A' = PAP^{-1}$$

Motivation: if we change β to β' then

$$\beta' [A]_{\beta'} = \underbrace{\beta' [I]_{\beta}}_{P} [A]_{\beta} \underbrace{[I]_{\beta'}}_{P^{-1}}$$

$P \xleftarrow{\text{Inverse!}} P^{-1}$

[The fact that column ops are forced by the row ops means that simplification does not occur by GE.]

\Rightarrow New approach is needed to "understand"

the operator: Spectral theory

eigenvector analysis

What kind of operations are there?

$$L(V, V).$$

$$[\mathbf{0}]_{\beta} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \text{indep. of basis!}$$

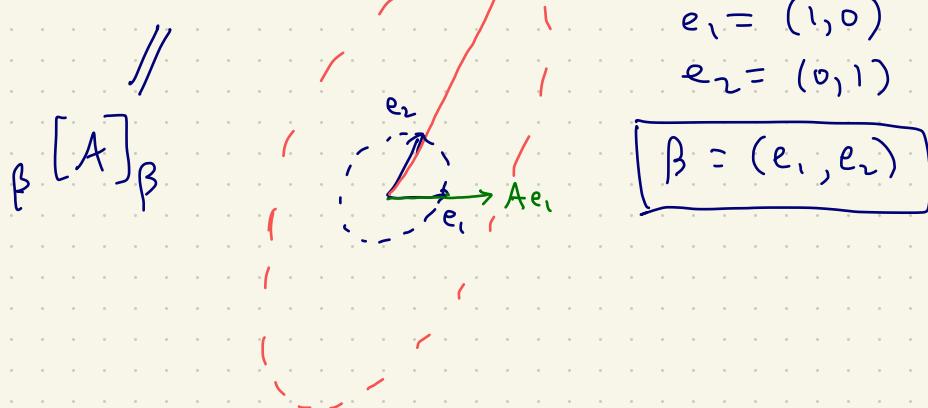
$$0) \quad 0 : v \mapsto 0 \quad \forall v.$$

$$1) \quad I : v \mapsto v \quad \forall v$$

$$[\mathbf{I}]_{\beta} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$2) \quad \lambda \in F \quad \lambda I : v \mapsto \lambda v \quad [\lambda I]_{\beta} = \begin{bmatrix} \lambda & & & 0 \\ & \lambda & & \\ 0 & & \lambda & \\ & & 0 & \lambda \end{bmatrix}$$

$$3) \quad A = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} \leftarrow \text{operator on } F^2 \quad \text{written in std basis}$$



While this operator is simple/easy to understand when written as above, if we change basis, won't be simple:

$$\text{eg} \quad \begin{bmatrix} \lambda_1 = 1 \\ \lambda_2 = 2 \end{bmatrix} \quad \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} = \begin{pmatrix} \frac{3}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{3}{2} \end{pmatrix}$$

$P \quad A \quad P^{-1}$

$e'_2 \leftarrow \begin{pmatrix} e_2 & e_1 \end{pmatrix} \quad e'_1 \rightarrow$

$\underbrace{\beta' \begin{bmatrix} I \end{bmatrix}_{\beta} \beta [A]_{\beta} \beta \begin{bmatrix} I \end{bmatrix}_{\beta}}_{\text{same operator!}} \quad \beta' = \left(\begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}, \begin{pmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} \right) = (e'_1, e'_2)$

different basis!

In the above example,

e_1, e_2 play the role of "fixed pts"

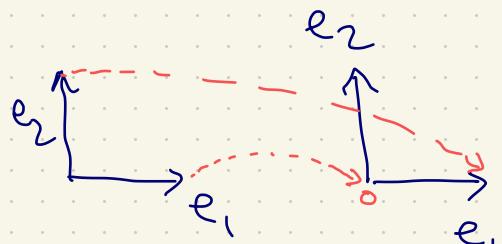
e'_1, e'_2 not

e_1, e_2 are examples of **Eigenvectors**.

the scale factors λ_1, λ_2 are **Eigenvalues**
examples of

4) besides eigenvectors, there is another type of behaviour: **Cycles**

e.g. $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$



one eigenvect.

$$\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\begin{array}{l} e_1 \mapsto 0 \\ e_2 \mapsto e_1 \\ e_3 \mapsto e_2 \end{array}$$

$\beta = (e_1, \dots, e_n)$ basis for V

$\beta' = (e'_1, \dots, e'_n)$ $e'_i \in V^*$

$$e'_i(e_i) = 1$$

$$(e'_i(e_2) = 0)$$

:

$$e'_i(e_n) = 0$$

$$\boxed{e'_i(e_j) = \begin{cases} 1 & i=j \\ 0 & \text{else} \end{cases}}$$

Prop

β' is lin. indep: let

$$\underbrace{a_1 e'_1 + \dots + a_n e'_n}_{=0} = 0$$

WTS $a_i = 0 \quad \forall i$.

strategy: Show $a_1 = 0$, then show $a_2 = 0$,

apply LHS to e_i : $a_1 e'_1(e_i) + a_2 e'_2(e_i) + \dots \rightarrow$

$$= a_1$$

$$\} \Rightarrow a_1 = 0$$

RHS to e_1 : $0(e_1) = 0.$

$$\text{apply LHS to } e_2 \quad a_1 e_1'(e_2) + a_2 e_2'(e_2) + \dots = a_2$$

$$\text{RHS to } e_2 = 0, \quad \left. \begin{array}{l} \\ a_2 = 0 \end{array} \right\}$$

repeat. ... □

$$e_1' \nearrow \swarrow e_2'$$

$$e_1' + e_2' = 0$$

apply LHS to e_1

$$e_1'(e_1) + e_2'(e_1) = 1 + 0 \\ = 1.$$

RHS = 0 $\neq 0 \#.$

Polynomials : $x^2 + 1 \neq (x - \lambda_1)(x - \lambda_2)$

extend ||
numbers
 $(x-i)(x+i)$ real

once the extension $\mathbb{R} \subset \mathbb{C}$ is done, we can factor all polynomials

$$p(z) = a_0 + a_1 z + a_2 z^2 + \cdots + a_n z^n$$

$$a_i \in \mathbb{C}$$

$$= a_n (z - \lambda_1) (z - \lambda_2) \cdots (z - \lambda_n)$$

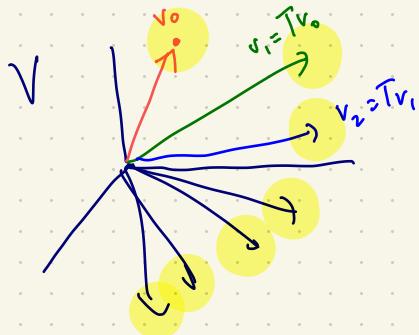
\mathbb{C}

V
f.d.v.sp / \mathbb{R}

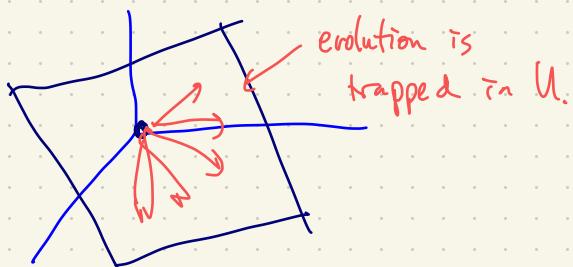
$$T \in L(V, V)$$

Def: Invariant subspace $U \subseteq V$ linear subspace

st. $T(U) \subseteq U$ i.e. $Tu \in U \forall u \in U$.



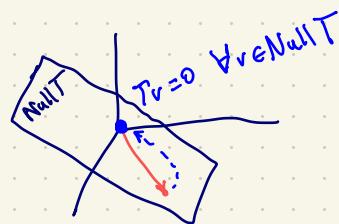
given $T \in L(V, V)$



evolution is
trapped in U .

Ex: ① $\{0\} \subseteq V$ invt.

① Null T



② Range(T) i.e. $\exists v \in V \quad u = Tv$

$$\begin{matrix} \downarrow \\ u \\ Tu = Tu \end{matrix}$$

$Tu \in \text{Range}(T)$.

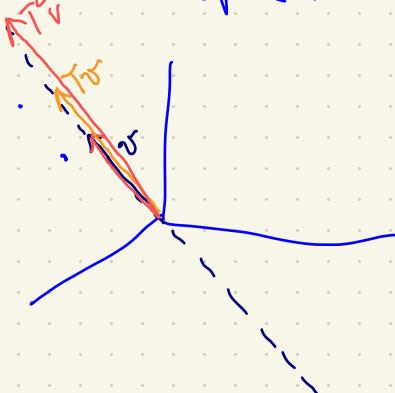
Defⁿ: an **eigenvalue** of T is a number $\lambda \in \mathbb{F}$

s.t. $\exists v$ nonzero with $v \in \text{Null}(T - \lambda I)$

$$Tv = \lambda v$$

$$(T - \lambda I)v = 0$$

The set of eigenvalues in \mathbb{F} is called the **SPECTRUM**
notice this means $\text{Span}(v)$ is an invariant subspace of T



Warning:

$0 \in \mathbb{F}$ is
a valid eigenval.

Any $v \neq 0$ in $\text{Null}(T)$ is an eigenvector with eigenvalue 0.

How to find eigenvectors?

Solve $Av = \lambda v$

i.e. $(A - \lambda I)v = 0$

2-step procedure

① find value λ s.t. $A - \lambda I$ has nullity > 0

i.e. $A - \lambda I$ not injective

i.e. $A - \lambda I$ not surjective.

i.e. $\text{rank}(A - \lambda I) < \dim V$.

② once found specific λ , " λ_1 " must find nonzero

$v \in \text{Null}(A - \lambda_1 I)$

Eg.: $A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 2 & -5 & 4 \end{pmatrix}$

(note Null A = {0}
so 0 not eigenvalue.)

① $A - \lambda I = \begin{pmatrix} -\lambda & 1 & 0 \\ 0 & -\lambda & 1 \\ 2 & -5 & 4-\lambda \end{pmatrix}$

Q.: When does this have nonzero null space.

A: do GE

$$\begin{array}{ccc} -2\lambda & 2 & 0 \\ 0 & -\lambda & 1 \\ \cancel{2} & \cancel{-5} & \cancel{\lambda(4-\lambda)} \\ \hline 0 & -2-5\lambda & \lambda(4-\lambda) \\ \hline 0 & 2 & \lambda(4-\lambda)-5 \\ \hline 0 & 2\lambda & \lambda(\lambda(4-\lambda)-5) \\ \hline 0 & 0 & \lambda(\lambda(4-\lambda)-5)+2 \end{array}$$

factor this

$$\begin{pmatrix} -2\lambda & 2 & 0 \\ 0 & -\lambda & 1 \\ 0 & 0 & -(\lambda-1)^2(\lambda-2) \end{pmatrix}$$

$$\lambda=1 \rightarrow \begin{pmatrix} -2 & 2 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

vector
in null space
of this.

this will have nonzero Null space $\Leftrightarrow \lambda=1$ or

$$\lambda=2$$

$\Rightarrow \lambda=1, \lambda=2$ are

the 2 eigenvalues for this operator.

eigenvector
for
 $\lambda=1$

choose $\lambda=1$ first plug in explicit value.

Thm: (Existence of an eigenvalue over $\mathbb{F} = \mathbb{C}$)

Pf: suppose $\dim V = n$ choose any nonzero vector $v \in V$.

$(v, T v, T^2 v, T^3 v, \dots, T^n v) \leftarrow$ MUST BE LIN DEP!!!

i.e. $\exists a_i$ not all zero s.t.

$$a_0 v + a_1 T v + \dots + a_n T^n v = 0$$

$$(a_0 I + a_1 T + a_2 T^2 + \dots + a_n T^n) v = 0$$

View this as a polynomial.
with coeffs in field \mathbb{C} !

$$= a_n (T - r_1 I) (T - r_2 I) \cdots (T - r_n I). v$$

\nearrow Roots of $p(z)$ in \mathbb{C} .

product of $(T - r_k I)$ has nonzero null space
i.e. not invertible

\Rightarrow at least one of the factors is not invertible,

i.e. $(T - r_i I)$ has a nonzero null space
 \Rightarrow eigenval $\lambda_1 = r_i$.
eigenvector is ?? find it.

if we can find a basis of eigenvectors

$$\beta = (e_1, \dots, e_n)$$

Then $\beta [T] \beta^{-1} = \begin{bmatrix} \lambda_1 & 0 & 0 & & \\ 0 & \lambda_2 & 0 & & \\ \vdots & 0 & \lambda_3 & \ddots & \\ 0 & 0 & 0 & \ddots & \lambda_n \end{bmatrix}$

this finding

of a basis of

eigenvectors

is called

"Diagonalization".

Diagonal

Matrix.

Thm

v_1, v_2 eigenvectors with eigenvalues
 λ_1, λ_2 and $\lambda_1 \neq \lambda_2$.

Then (v_1, v_2) lin. indep.

Pf: suppose $a_1 v_1 + a_2 v_2 = 0$ ①

then apply T

$$a_1 T v_1 + a_2 T v_2 = T_0 = 0$$



$$a_1 \lambda_1 v_1 + a_2 \lambda_2 v_2 = 0 \quad \text{②}$$

Want to show $a_1 = 0$ and $a_2 = 0$

to show $a_1 = 0$: take $\lambda_2 \textcircled{①} - \textcircled{②}$

$$a_1 (\underbrace{\lambda_2 - \lambda_1}_{\neq 0}) \underbrace{v_1}_{\neq 0} = 0 \Rightarrow \boxed{a_1 = 0}$$

$a_2 = 0$: take $\lambda_1 \textcircled{①} - \textcircled{②}$ ③

$$a_2 (\lambda_1 - \lambda_2) v_2 = 0$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = A$$

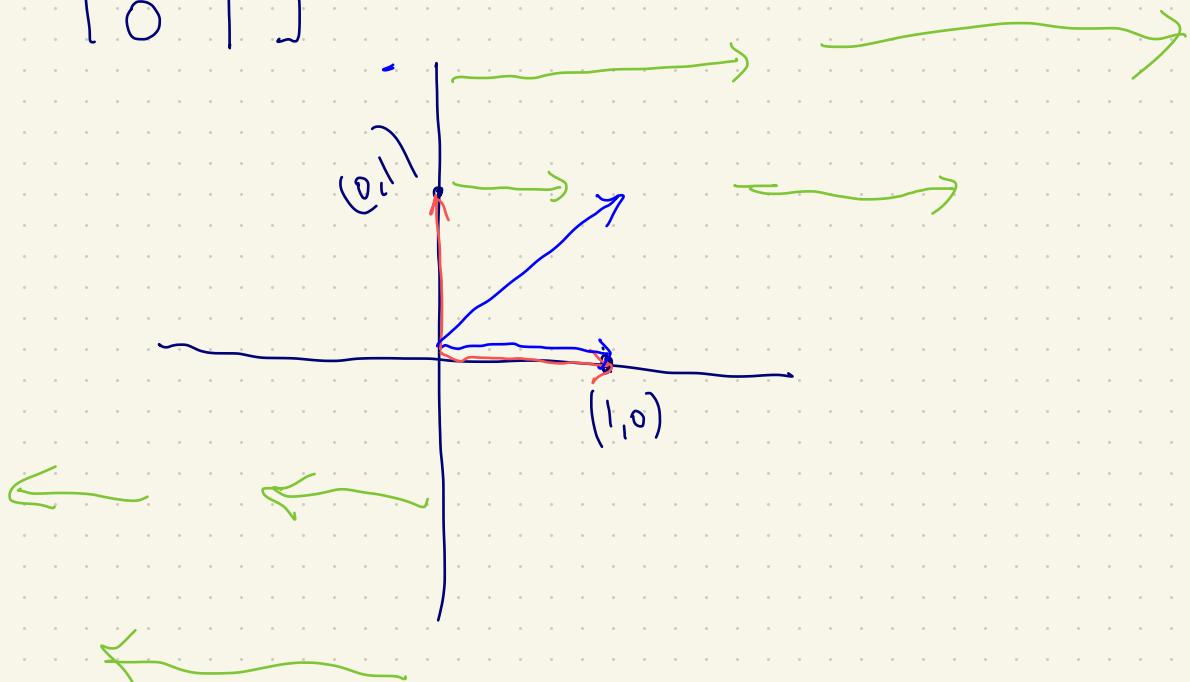
$$Ae_1 = e_1$$

$$Ae_2 = e_2$$

Single eigenvalue 2d space of
eigenvectors.

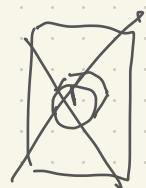
$$\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

$$Ae_1 = e_1$$



$$\begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \quad \begin{array}{l} e_1 \mapsto e_1 \\ e_2 \mapsto e_2 + e_1 \\ e_3 \mapsto e_3 + e_2 \\ \vdots \\ e_n \mapsto e_n + e_{n-1} \end{array}$$

$$A - 1I = \begin{bmatrix} 0 & 1 & & \\ 0 & 1 & & \\ 0 & 1 & & \\ 0 & 0 & & \end{bmatrix} \quad \begin{array}{l} e_1 \mapsto 0 \\ e_2 \mapsto e_1 \\ e_3 \mapsto e_2 \\ e_4 \mapsto e_3 \end{array}$$



$$q: S \rightarrow \mathbb{C}$$

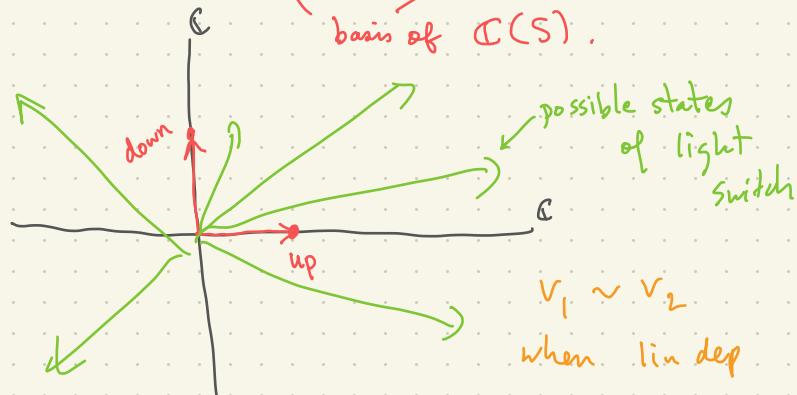
$$q(\text{up}) = 1$$

$$q(\text{down}) = -1$$

$\begin{cases} 1 & \text{Space of states} = \{\text{up, down}\} = S \\ -1 & \end{cases}$

$$\mathbb{C}(S) = \{a_1(\text{up}) + a_2(\text{down}) : a_1, a_2 \in \mathbb{C}\}$$

basis of $\mathbb{C}(S)$.



In Quantum mechanics, the light switch has Quantum state = a vector in $\mathbb{C}(S)$

Operator: "Position" operator Q

$$Q = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$Q(\text{up}) = Q \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

up is eigenvector w/ eigenval 1
down " " " " " " " " -1.

$$Q \begin{pmatrix} -1 \\ 0 \end{pmatrix} = \textcircled{1} \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

classic state up

