Due date: November 19, 2009

Please contact me if there are any errors.

**Exercise 1.** A smooth map  $f : X \longrightarrow Y$  is said to be transverse to an embedded submanifold  $Z \subset Y$  when f is transverse to the inclusion map  $\iota : Z \hookrightarrow Y$ . Assuming X is compact and Z closed, show that the transversality of f to Z is stable under perturbations of f.

**Exercise 2.** Let M, N be embedded submanifolds of a manifold X, and suppose that their intersection  $M \cap N$  is an embedded submanifold. Then M, N are said to have *clean* intersection when, for each  $p \in M \cap N$ , we have  $T_p(M \cap N) = T_pM \cap T_pN$ .

- i) Can the intersection of embedded submanifolds be transverse but not clean? Can it be clean but not transverse? Give examples or proofs as necessary.
- ii) If K, K' are cleanly intersecting submanifolds of X, of codimension k, k' respectively, show that there is a neighbourhood U of any point p ∈ K ∩ K', and coordinates x<sup>1</sup>,..., x<sup>n</sup> on U such that K ∩ U = {x<sup>1</sup> = ··· = x<sup>k</sup> = 0} and L ∩ U = {x<sup>j</sup> = ··· = x<sup>j+k'-1</sup> = 0}, for some j ≤ k + 1.
- iii) Let M, N intersect cleanly in X, and let  $g: G \longrightarrow M$  and  $h: H \longrightarrow N$  be submersions. Is  $G \times_X H := G_{\iota_M \circ g} \times_{\iota_N \circ h} H$  an embedded submanifold of  $G \times H$ ? (here  $\iota_M, \iota_N$  are the inclusions). Justify your claim.

## Exercise 3.

Compute the mod 2 self-intersection number of the zero section  $X \longrightarrow TX$  for the manifolds  $X \in \{S^1, S^2, \mathbb{R}P^2\}$ . Deduce that every smooth vector field on  $\mathbb{R}P^2$  must have a zero.

**Exercise 4.** Let X be compact and  $f : X \longrightarrow Y$  smooth with dim  $X = \dim Y$  and Y connected. Recall that the mod 2 degree of f is defined in terms of the mod 2 intersection number as follows: deg<sub>2</sub>(f) =  $I_2(f, \iota)$ , where  $\iota : y \mapsto Y$  is the inclusion map of a point  $y \in Y$ .

- i) Prove that  $\deg_2(f)$  is independent of the point  $y \in Y$ .
- ii) If Y is non-compact, prove that  $deg_2(f) = 0$ .
- iii) A map f : X → Y is called *essential* when it is not homotopic to a constant map. Prove that if deg<sub>2</sub>(f) = 1, then f is essential.
- iv) Give example of a smooth surjective map  $f: S^2 \longrightarrow S^2$  with deg<sub>2</sub>(f) = 0.
- v) Can there exist a smooth map  $f: S^2 \longrightarrow T^2$  with  $\deg_2(f) = 1$ ? [Hint: consider two embedded circles  $C_1, C_2$  in  $T^2$  intersecting transversally at a single point.] Can there exist a smooth map of  $\deg_2(f) = 1$  in the opposite direction? In each case, give proofs.

**Exercise 5.** Let (x, y, z) be the standard coordinates on  $\mathbb{R}^3$  and consider the 1-form  $\theta = dx + ydz \in \Omega^1(\mathbb{R}^3)$ . Does there exist a smooth immersion f from a neighbourhood of the origin in  $\mathbb{R}^2$  to  $\mathbb{R}^3$  such that  $f^*\theta = 0$ ? [Hint: see illustration on course webpage.] What if, instead,  $\theta = xdx + ydy + zdz$ ? Justify this result also.

**Exercise 6.** Consider  $S^n$  and its two stereographic coordinate charts  $\varphi_S, \varphi_N$  to  $\mathbb{R}^n$ . Using standard coordinates on  $\mathbb{R}^n$ , write down the coordinate expressions for a smooth, nowhere-vanishing *n*-form on  $S^n$ .